

# Networks - Fall 2005

## Chapter 1















### Network formation

October 25, 2005

# Summary

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- WHAT IS A NETWORK?  
- JACKSON-WOLINSKY MODEL(S)  
- STABILITY AND EFFICIENCY  
- EXISTENCE AND PW-STABILITY  
- MULTIPLICITY AND PW-STABILITY  
- THE MYERSON GAME  
- PAIRWISE NASH EQUILIBRIA  



# WHAT IS A NETWORK? (1/3)



- A collection of “entities” (nodes) and bilateral relationships (links).

The *links/relationships* can be:

**Directed** : Not necessarily reciprocal.

**Undirected** : Always reciprocal.

**Weighted** : Some links are more “equal” than others.

**Stochastic** : The links are realized with some probability.

# WHAT IS A NETWORK? (2/3)



Two crucial characteristics of networks:

- A** : Interactions are not anonymous (as opposed to standard “market” transactions.)
  
- B** : The particular place agents occupy in the set of relationships is important.

# WHAT IS A NETWORK? (3/3)



Network does potentially two things:

1. Production  $\implies$  Efficiency.
2. Allocation  $\implies$  Stability.

The interaction between the two produces a tension for network formation.

**Q1** Which is the efficient productive network?

**Q2** What is the stable network?

**Q3** Are efficient networks stable and vice versa?



## THE GENERAL MODEL

Let  $N = \{1, 2, \dots, n\}$  be the set of all individual nodes.

We denote by  $ij$  a potential link between players  $i, j \in N$ .

A graph  $g$  is a collection of *undirected* links  $ij$ .

We assume  $ii \notin g$ .

Let  $N(g) = \{j \in N : \exists ij \in g\}$ , and  $n(g)$  the cardinality of  $N(g)$ .

Let  $N_i(g) = \{j \in N : ij \in g\}$ , and  $n_i(g)$  the cardinality of  $N_i(g)$ .

*Payoff functions* for each player:  $u_i : g \rightarrow \mathbb{R}$ .



*Distance:* We denote by  $d_{ij}(g)$  the shortest (geodesic) distance between  $i$  and  $j$  in  $g$ .

*Components:* The graph  $g' \subset g$  is a *component* of  $g$  if for all  $i, j \in N(g')$  ( $i \neq j$ ), there exists a path in  $g'$  connecting  $i$  and  $j$ , and for any  $i \in N(g')$ ,  $j \in N(g)$  if  $ij \in g$ , then  $ij \in g'$ .



## PARTICULAR MODELS

### MODEL 1-CONNECTIONS:

$$u_i(g) = \sum_{j \neq i} \delta^{d_{ij}(g)} - c \cdot n_i(g), \quad 0 < \delta < 1, \quad c \geq 0.$$

- Never detrimental to third parties if two agents creates a link between them (positive externality.)
- Two connections can have different effects on a player.



MODEL 2-CO-AUTHOR:

$$u_i(g) = \sum_{ij \in g} \left[ \frac{1}{n_i(g)} + \frac{1}{n_j(g)} + \frac{1}{n_i(g)n_j(g)} \right].$$

$$u_i(g) = 0 \text{ if } n_i(g) = 0.$$

$$u_i(g) = 1 + \left(1 + \frac{1}{n_i}\right) \sum_{ij \in g} \left[ \frac{1}{n_j(g)} \right].$$

Never beneficial to third parties if two agents creates a link between them (negative externality.)

- *Efficiency*: Let  $W(g) = \sum_{i \in N} u_i(g)$ . We say  $g^*$  is *efficient* iff  $W(g^*) \geq W(g) \forall g$ .

Notice that this notion is *utilitarian* not *Paretian*.

- *Stability*: We say that a network  $g'$  is *pairwise stable* iff:

1.  $u_i(g') \geq u_i(g' - ij)$  and  $u_j(g') \geq u_j(g' - ij)$ ,  $\forall ij \in g$ .

2.  $u_i(g' + ij) > u_i(g') \Rightarrow u_j(g' + ij) < u_j(g')$ ,  $\forall ij \notin g$ .

- Notice that:

- Only checks single link deviation.
- Checks bilateral creation and unilateral cutting.

## EFFICIENCY IN CONNECTIONS MODEL

$$u_i(g) = \sum_{j \neq i} \delta^{d_{ij}(g)} - c \cdot n_i(g), 0 < \delta < 1, c \geq 0.$$

1. The *complete* graph is *efficient* if  $c < \delta - \delta^2$ .

$\delta - \delta^2$  is *minimum* increased benefit from a new direct link.

Cost of a direct link  $c$

2. A *star* encompassing  $N$  is *efficient* if  $\delta - \delta^2 < c < \delta + ((N - 2)/2)\delta^2$ .

3. *No links* are *efficient* if  $\delta + ((N - 2)/2)\delta^2 < c$ .



## 4. Proof of 2+3:

- Let a component  $g'$  with  $m$  nodes and  $k$  links.
- Value of direct links is  $k(2\delta - 2c)$ .
- Maximum value of indirect links  $(m(m - 1)/2 - k)2\delta^2$ .
- So  $W(g') \leq \bar{W} = k(2\delta - 2c) + (m(m - 1) - 2k)\delta^2$ .
- $W(m - star) = (m - 1)(2\delta - 2c) + (m - 1)(m - 2)\delta^2$ .
- Thus  $\bar{W} - W(m - star) = (k - (m - 1))(2\delta - 2c - 2\delta^2) \leq 0$ .  
(since  $k \geq m - 1$  and  $\delta - \delta^2 < c$ ).
- Thus every *component* of *efficient* graph must be a star. A star of  $m + n$  is more efficient than two separate stars.
- And  $W(star) \geq 0 \Leftrightarrow \delta + \frac{m-2}{2}\delta^2 \geq c$ .



## STABILITY IN CONNECTIONS MODEL

1. The *complete* graph is *pairwise stable* if  $c < \delta - \delta^2$ .

Same reason as before, argument was pairwise.

2. *Pairwise stable* networks are always *fully connected*.

- For a contradiction, assume  $g$  has pw-stable subcomponents  $g', g''$ .
- Let  $ij \in g'$ , and  $kl \in g''$ .
- Then pw-stability of  $g' \Rightarrow u_i(g) - u_i(g - ij) \geq 0$ .
- But,  $u_k(g + kj) - u_k(g) > u_i(g) - u_i(g - ij)$ , since any new benefit that  $i$  gets from  $j$ ,  $k$  also gets and in addition  $k$  gets  $\delta^2$  times the benefits of  $i$ 's connections.
- Similarly,  $u_j(g + jk) - u_j(g) > u_l(g) - u_l(g - lk) \geq 0$ .
- This contradicts pw-stability since  $jk \notin g$ .



3. For  $\delta - \delta^2 < c < \delta$  star is pw-stable, but not always uniquely so.

- Deleting means losing at least  $\delta$  and gaining  $c$ .
- Adding  $ij$  : net gain  $\delta - \delta^2$ , cost  $c$ .
- For  $N = 4$ , and  $\delta - \delta^3 < c < \delta$ , the line is also pw-stable.
- For  $N = 4$ , and  $\delta - \delta^3 > c > \delta - \delta^2$ , the circle is also pw-stable.



4. For  $\delta < c$ , any non-empty network is inefficient.

- For  $\delta < c$ , connection  $ij$  is unprofitable to  $i$  if  $N_j(g) = i$  (cost to  $i$  is  $c$ , benefit  $\delta$ ).
- Star is not stable.
- For  $N = 5$ , and  $\delta - \delta^4 + \delta^2 - \delta^3 > c$ , the circle is pw-stable (deleting one link benefit is  $\delta - \delta^4 + \delta^2 - \delta^3$ , cost is  $c$ ; adding one link benefit is  $\delta - \delta^2$ , cost is  $c$ ).





## EFFICIENCY IN CO-AUTHOR MODEL

1. For  $n$  even, the efficient network is  $n/2$  pairs.

$$W(g) = \sum_{i \in N} u_i(g) = \sum_{i: n_i(g) > 0} \sum_{ij \in g} \left[ \frac{1}{n_i} + \frac{1}{n_j} + \frac{1}{n_i n_j} \right]$$

But since  $\sum_{i: n_i(g) > 0} \sum_{ij \in g} \left[ \frac{1}{n_i} \right] \leq n$  (equality only if  $n_i > 0$  for all  $i$ )

$$W(g) \leq 2n + \sum_{i: n_i(g) > 0} \sum_{ij \in g} \left[ \frac{1}{n_i n_j} \right]$$



But

$$\sum_{i:n_i(g)>0} \sum_{ij \in g} \left[ \frac{1}{n_i n_j} \right] = \sum_{i:n_i(g)>0} \frac{1}{n_i} \sum_{ij \in g} \left[ \frac{1}{n_j} \right] \leq n$$

(since  $\sum_{ij \in g} \left[ \frac{1}{n_j} \right] \leq n_i$ ) and equality can only be achieved if  $n_j = 1$  for all  $j \in N$ .

## STABILITY IN CO-AUTHOR MODEL

1. *Pairwise stable* networks are composed of fully intra-connected components of different sizes.

Let  $i$  and  $j$  not linked.

$$u_i(g + ij) = 1 + \left(1 + \frac{1}{n_i + 1}\right) \left[ \frac{1}{n_j + 1} + \sum_{ik \in g} \frac{1}{n_k} \right].$$

A new link  $ij$  is beneficial to  $i$  iff:

$$\begin{aligned} \left(1 + \frac{1}{n_i + 1}\right) \frac{1}{n_j + 1} &> \left(\frac{1}{n_i} - \frac{1}{n_i + 1}\right) \sum_{ik \in g} \frac{1}{n_k} \\ \left(\frac{n_i + 2}{n_i + 1}\right) \frac{1}{n_j + 1} &> \left(\frac{1}{n_i(n_i + 1)}\right) \sum_{ik \in g} \frac{1}{n_k} \\ \frac{n_i + 2}{n_j + 1} &> \frac{1}{n_i} \sum_{ik \in g} \frac{1}{n_k} \end{aligned}$$



(a) If  $n_i = n_j$   $i$  wants  $j$  and vice versa.

$$\frac{1}{n_i} \sum_{ik \in g} \frac{1}{n_k} \leq 1 \text{ (average of fractions.)}$$

So if  $n_i \geq n_j$  linking to  $j$  is beneficial for  $i$ . When  $n_i = n_j$  this is reciprocal.

- (b) If  $n_h \leq \max\{n_k | ik \in g\}$  then  $i$  wants a link to  $h$ .  
 Let  $j$  such that  $ij \in g$  and  $n_j = \max\{n_k | ik \in g\}$ .

**Case 1**  $n_i \geq n_j - 1$

$$\frac{n_i + 2}{n_h + 1} \geq \frac{n_i + 2}{n_j + 1} \geq 1 \left\{ \begin{array}{l} \frac{n_i + 2}{n_h + 1} > 1 \Rightarrow i \text{ wants } h \\ \frac{n_i + 2}{n_h + 1} = 1 \Rightarrow n_h \geq 2 \Rightarrow n_j \geq 2 \\ \Rightarrow \frac{1}{n_i} \sum_{ik \in g} \frac{1}{n_k} < 1 \Rightarrow i \text{ wants } h \end{array} \right.$$

**Case 2**  $n_i < n_j - 1$

$$\frac{n_i + 2}{n_h + 1} \geq \frac{n_i + 2}{n_j + 1} = \frac{n_i + 1 + 1}{n_j + 1} > \frac{n_i + 1}{n_j}$$

Since  $ij \in g$  this implies

$$\frac{n_i + 1}{n_j} \geq \frac{1}{n_i - 1} \sum_{\substack{ik \in g \\ k \neq j}} \frac{1}{n_k} \geq \frac{1}{n_i} \sum_{ik \in g} \frac{1}{n_k}$$

The last inequality holds since the extra term  $1/n_j$  is smaller than other in the average. Thus,

$$\frac{n_i + 2}{n_h + 1} \geq \frac{1}{n_i} \sum_{ik \in g} \frac{1}{n_k}$$



(c) If  $m$  is the number of members in one component, and  $n$  in the next largest, then  $m > n^2$ .

Let  $j$  in a component and  $i$  in the next largest.  $i$  does not want  $j$  iff:

$$\frac{n_i + 2}{n_j + 1} \leq \frac{1}{n_i} \Rightarrow n_j + 1 \geq (n_i + 2) n_i \Rightarrow n_j \geq n_i^2$$

The first inequality is true since all connections of  $i$  have  $n_i$  connections.

**Remark** a) implies that all  $i$  with maximal  $n_i$  have to be inter-linked.

b) implies that if  $j$  is linked to one  $i$  with maximal  $n_i$ ,  $j$  wants to be linked to all other  $k$  with maximal  $n_k$  and those with whom they are themselves connected.

So fully intra-connected components at maximum. Then, iterate.



- Evidence of “connectedness” in science in:
  - Newman (2004) PNAS.
  - Goyal, van der Leij, Moraga (2004).
- Seems like over-connected.
- Tension between stability and efficiency is well-captured by pw-stability.
- Positive issues in pw-stability: *Existence*.



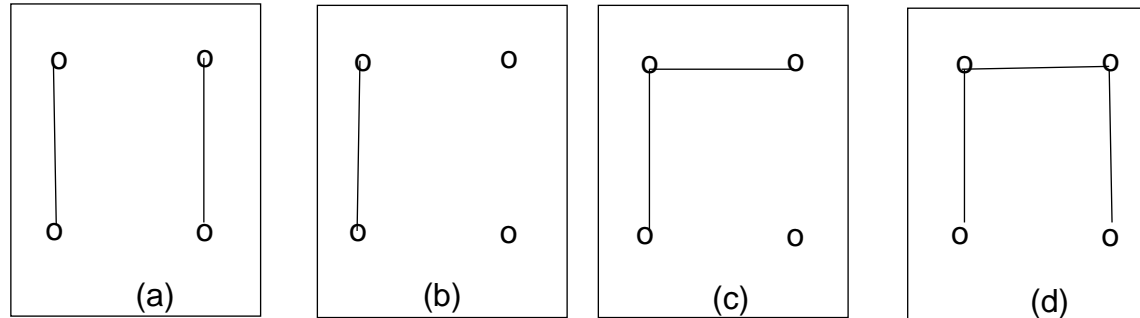
## *Trading networks*

- Set of players  $N = \{1, \dots, n\}$ , players are nodes of a network  $g$ .
- Endowments for player  $i$  stochastic:  $(x_i, y_i) \in \{(1, 0), (0, 1)\}$  equally likely.
- Production function:  $f(x, y) = x \cdot y$ .
- Trade is possible between agents  $i$  and  $j$  if they belong to the same component.
- Let  $P = \{i_0, i_1, \dots, i_p\} \subset N$ , such that  $g|_P$  is a component of  $g$ .



- Trading outcome for a player  $i \in P$  is:  $\omega_i = \frac{1}{p+1} \left( \sum_{k=0}^p x_{i_k}, \sum_{k=0}^p y_{i_k} \right)$ .
- That is, endowments are aggregated within connected component and shared equally.
- Cost of every link is  $c$ .
- Network formation is done *before* endowments are realized (need to use expected payoffs.)

$n = 4$



1.(a)  $Eu_i = \frac{1}{2}f\left(\frac{1}{2}, \frac{1}{2}\right) - c = \frac{1}{8} - c$ , for all  $i \in N$ .

(b)  $Eu_i = \frac{1}{2}f\left(\frac{1}{2}, \frac{1}{2}\right) - c$  for  $i \in \{1, 2\}$  and  $Eu_i = 0$  for  $i \in \{3, 4\}$ .

(c)  $Eu_i = \frac{6}{8}f\left(\frac{2}{3}, \frac{1}{3}\right) - c = \frac{1}{6} - c$  for  $i \in \{1, 3\}$ ,  $Eu_i = \frac{1}{6} - 2c$  for  $i = 2$ , and  $Eu_i = 0$  for  $i = 4$ .

(d)  $Eu_i = \frac{8}{16}f\left(\frac{3}{4}, \frac{1}{4}\right) + \frac{6}{16}f\left(\frac{2}{4}, \frac{2}{4}\right) - c = \frac{3}{16} - c$  for  $i \in \{1, 4\}$ , and  $Eu_i = \frac{3}{16} - 2c$  for  $i \in \{2, 3\}$ .

2. (b) is not stable for  $c \leq \frac{1}{8}$  since players 3 and 4 would like to create a link.
3. (a) is not stable for  $c \leq \frac{3}{16} - \frac{1}{8} = \frac{1}{16}$  since players 2 and 3 would like to create a link.
4. (d) is not stable for  $c \geq \frac{3}{16} - \frac{1}{6} = \frac{1}{48}$  since player 3 would like to delete link 34.
5. (c) is not stable for  $c \geq \frac{1}{6} - \frac{1}{8} = \frac{1}{24}$  since player 2 would like to delete link 23.
6. All other configurations are unstable since links are redundant.

These observations together imply that for  $\frac{1}{24} \leq c \leq \frac{1}{8}$  there is no stable *trading network*.



## DYNAMIC STABILITY

- For many parameters/payoff functions (e.g. co-author) there are multiple pw-stable networks.
- In games one approach to decrease multiplicity is evolutionary dynamics.
- In particular - *stochastic stability*
  - Young, or, Kandori, Mailath and Rob, both 1993 *Econometrica*



- Stochastic process:
  - State variable - past actually played strategies (perhaps time-averaged.)
  - Updating rule/transition probabilities:
    - Best-response (or better-response) to state - with prob.  $1 - \varepsilon$ .
    - Anything else - with probability  $\varepsilon$ .
- Stochastic process reaches all states with positive probability.
- Thus, it is ergodic and has a stationary distribution  $\mu^\varepsilon$ .
- *Stochastically stable states* are those with positive probability in  $\bar{\mu} = \lim_{\varepsilon \rightarrow 0} \mu^\varepsilon$ .

- *Stochastically stable networks*
  - State variable: network  $g$ .
  - Updating rule: one-link deviation possibility.
  - Example: co-author model - two pw-stable networks.
  - More mistakes are needed to do one transition than the other.

# THE MYERSON GAME (1/9)



- Set of players:  $N = \{1, \dots, n\}$ .
- Strategy set:  $S_i = \{0, 1\}^{n-1}$ .
- Let strategy  $s_i = (s_{i1}, s_{i2}, \dots, s_{in}) \in S_i$ 
  - $s_{ij} = 0$  if  $i$  does not want to link to  $j$ ,
  - $s_{ij} = 1$  if  $i$  wants to link to  $j$ .
- $s = (s_1, \dots, s_n) \in S$  is a strategy profile.
- Let  $g(s)$  be the network that arises from  $s$ .
- For  $g(s)$ , let  $g_{ij}(s) \in \{0, 1\}$  denote the presence of absence of link  $ij$ .



- One-sided link formation (directed networks):  $g_{ij}(s) = s_{ij}$
- Two-sided link formation (undirected):  $g_{ij}(s) = s_{ij} * s_{ji}$ .
- Example of one-sided: Bala and Goyal (2000) *Econometrica*.

$$u_i(g) = \sum_{j \neq i} \delta^{d_{ij}(g)} - c \cdot n_i(g), 0 < \delta < 1, c \geq 0.$$

## MULTIPLICITY IN MYERSON GAMES: REFINEMENTS

- Let:

$s_1 \backslash s_2$	$s_{21}$	$s_{22}$
$s_{11}$	-2,-2	-2,-2
$s_{12}$	-2,-2	0,0

- *Trembling-hand perfect equilibrium* (THPE):
  - $\sigma^\varepsilon$  is a  $\varepsilon$ -constrained equilibrium if it is:
    1. Completely mixed.
    2.  $\sigma_i^\varepsilon \in \arg \max \{u_i(\sigma_i, \sigma_{-i}^\varepsilon) \mid \sigma_i(s_i) \geq \varepsilon(s_i)\}$ .
  - $\sigma$  is a THPE iff  $\sigma = \lim_{\varepsilon \rightarrow 0} \sigma^\varepsilon$  where  $\sigma^\varepsilon$  is some sequence of  $\varepsilon$ -constrained eq.

# THE MYERSON GAME (4/9)

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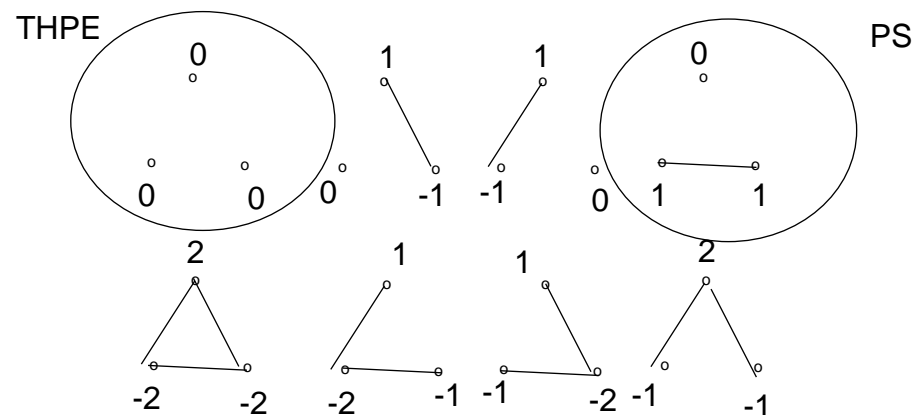


- $(s_{11}, s_{21})$  in the example is NE but not THPE.
- Unfortunately that is not general.

# THE MYERSON GAME (5/9)



**Claim 1** *THPE does not eliminate all “unwanted” Nash equilibria in the following Example.*



It is easy to see that the null graph is a Nash equilibrium, but not stable. We will now show it is a THPE.

Represent a mixed strategy  $\sigma \in \Delta\{0, 1\}^2$  as in:

# THE MYERSON GAME (6/9)



$$\sigma_1 = \begin{array}{c|cc} & s_{13} = 0 & s_{13} = 1 \\ \hline s_{12} = 0 & a & b \\ \hline s_{12} = 1 & c & 1 - a - b - c \end{array}$$

Then we will check that the following is an  $\varepsilon$ -constrained equilibrium (for sufficiently small  $\varepsilon$ .)

$$\sigma_1^\varepsilon = \begin{array}{c|cc} & s_{13} = 0 & s_{13} = 1 \\ \hline s_{12} = 0 & \varepsilon & \varepsilon \\ \hline s_{12} = 1 & \varepsilon & 1 - 3\varepsilon \end{array}, \quad \sigma_2^\varepsilon = \begin{array}{c|cc} & s_{23} = 0 & s_{23} = 1 \\ \hline s_{21} = 0 & 1 - 2\varepsilon^4 - \varepsilon & \varepsilon^4 \\ \hline s_{21} = 1 & \varepsilon^4 & \varepsilon \end{array},$$

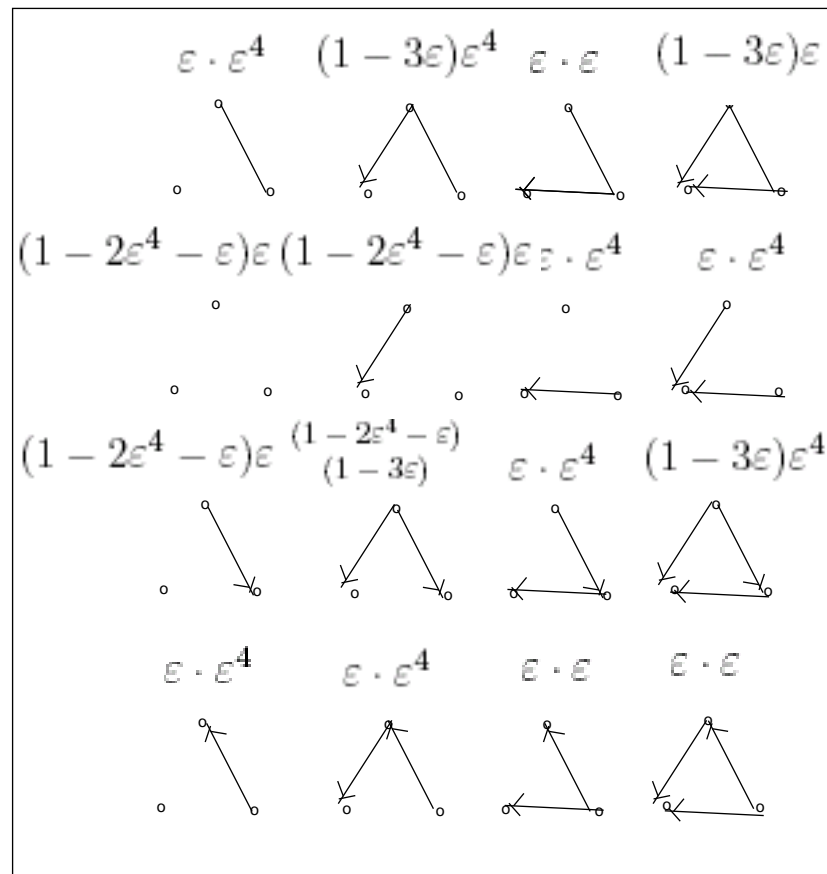
$$\sigma_2^\varepsilon = \begin{array}{c|cc} & s_{32} = 0 & s_{32} = 1 \\ \hline s_{31} = 0 & 1 - 2\varepsilon^4 - \varepsilon & \varepsilon^4 \\ \hline s_{31} = 1 & \varepsilon^4 & \varepsilon \end{array}$$

- Easy to check  $\sigma_1^\varepsilon$  is optimal. Player 1 has a dominant strategy to create as many links as possible.

# THE MYERSON GAME (7/9)



- Why is  $\sigma_2^\varepsilon$  optimal against  $\sigma_{-2}^\varepsilon = (\sigma_1^\varepsilon, \sigma_3^\varepsilon)$ ?



# THE MYERSON GAME (8/9)



Let  $u_2((s_{31} = 0, s_{32} = 1), \sigma_{-2}^\epsilon)$  and disregard terms of order  $\epsilon^2$  or more. Then

$$u_2((s_{31} = 0, s_{32} = 1), \sigma_{-2}^\epsilon) \approx ((1 - 3\epsilon)\epsilon + \epsilon^2) \cdot (-1) + 2\epsilon^2 \cdot 1 < 0$$

whereas

$$u_2((s_{31} = 0, s_{32} = 0), \sigma_{-2}^\epsilon) = 0$$

- Notice that it is crucial that the “mistake” of sending links to both 1 and 2 by player 3 is  $\epsilon$ , whereas the (less serious) of sending only to 3 is  $\epsilon^2$ .
- Thus *proper equilibrium* may be better.
  - $\sigma^\epsilon$  is a  $\epsilon$ -proper equilibrium if it is:
    1. Completely mixed.

$$2. \{u_i(s_i, \sigma_{-i}^\varepsilon) < u_i(s'_i, \sigma_{-i}^\varepsilon) \Rightarrow \sigma_i(s_i) < \varepsilon \cdot \sigma_i(s'_i)\}.$$

- $\sigma$  is a *proper equilibrium* iff  $\sigma = \lim_{\varepsilon \rightarrow 0} \sigma^\varepsilon$  where  $\sigma^\varepsilon$  is some sequence of  $\varepsilon$ -proper eq.
- $(s_{11}, s_{21})$  in the example is NE but not THPE.
- Unfortunately that is not general.



- Let again the (Myerson) network formation game.
- We say that  $g$  is *pairwise Nash* iff:
  - $g$  is a Nash equilibrium of the Myerson game.
  - $u_i(g + ij) > u_i(g) \Rightarrow u_j(g + ij) > u_j(g)$ .
- This is a Nash equilibrium for which every mutually beneficial link is created.
- A pairwise Nash network is robust to:
  - Bilateral single link creation.
  - Unilateral *multi*-link destruction.

- For the latter reason, this is more demanding than pw-stability.

- Pairwise stability:

$$g \in PS \Rightarrow u_i(g - ij) - u_i(g) \leq 0 \quad \forall i \in N, ij \in g \quad (*).$$

- Pairwise Nash:

$$g \in PN \Rightarrow u_i(g - ij_1 - ij_2 \dots - ij_p) - u_i(g) \leq 0 \quad \forall i \in N, ij_1, ij_2, \dots, ij_p \in g \quad (**).$$

- Obviously  $(**) \Rightarrow (*)$ . If  $(*) \Rightarrow (**)$ , then Pairwise stability and Pairwise Nash are equivalent.

- A condition guaranteeing this is  $u_i(\cdot)$  being  $\alpha$ -convex.

- $u_i(\cdot)$  is  $\alpha$ -convex iff

$$u_i(g - ij_1 - ij_2 \dots - ij_l) - u_i(g) \geq \alpha \sum_{k=1}^p (u_i(g - ij_k) - u_i(g)).$$

- To find  $\alpha$  take the

$$\min_{g' \subset g} \{u_i(g - ij_1 - ij_2 \dots - ij_l) - u_i(g)\} / \max_{ij_k} \{u_i(g - ij_k) - u_i(g)\}.$$

# Networks - Fall 2005

## Chapter 1

### Network formation

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