## Microeconomics II - Winter 2005

## Chapter 4

Games with Incomplete Information
Perfect Bayesian and Sequential equilibrium

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## Summary

- Examples $" \mathrm{~m} \rightarrow$
- (Weak) Perfect Bayesian and Sequential equilibrium $n \Rightarrow$
- WPBE and Sequential equilibria for examples $n \Rightarrow$


## Examples (1/4)

A Game B of chapter 2


## Examples (2/4)

B Beer-Quiche.


## Examples (3/4)

C Game with a WPBE equilibrium which is not sequential.


## Examples (4/4)

D Spence education model (Osborne-Rubinstein's version).

- A worker (sender) knows her ability $\theta$. The firm (receiver) does not.
- The value of the worker to the firm is $\theta$ and the wage the worker receives is the firm expectation of $\theta$ (competition plus equal expectations).
- Let's say to make it a "real" game that payoff of employer is $-(w-\theta)^{2}$ (the expectation of this is maximized at $w=E(\theta)$.)
- The worker sends a signal $e$, the level of education. Her payoff is $w-e / \theta$. There are two types of workers $\theta^{L}$ and $\theta^{H}$, with probabilities $p^{H}$ and $p^{L}$.


## (Weak) Perfect Bayesian and Sequential equilibrium (1/4)

Let a game

$$
\Gamma=\left\{N,\left\{K_{1}, \ldots, K_{n}\right\}, R,\left\{H_{1}, \ldots, H_{n}\right\},\{A(x)\}_{x \in K \backslash Z},\left\{\left(\pi_{1}(z), \ldots, \pi_{n}(z)\right\}_{z \in Z}\right\}\right.
$$

A (Weak) Perfect Bayesian equilibrium (WPBE) is a profile behavioral strategy such that there exist beliefs with:
a Strategies are optimal at all information sets, given the beliefs (for every node there is a belief $\mu(x) \geq 0$, with the requirement $\sum_{x \in h} \mu(x)=1$ ).
b Beliefs are consistent with the strategies and Bayes rule, wherever possible.

Why wherever possible? Because some information sets may not be visited in equilibrium (remember example A).

## (Weak) Perfect Bayesian and Sequential equilibrium (2/4)

Formally:

Definition 1 A behavioral strategy profile $\gamma^{*}=\left(\gamma_{1}^{*}, \ldots, \gamma_{n}^{*}\right) \in \Psi$ is a weak perfect Bayesian equilibrium for game $\Gamma$ if there exists a system of beliefs $\mu^{*}=\left\{\left(\mu^{*}(x)\right)_{x \in h}\right\}_{h \in H}$ such that the assessment $\left(\gamma^{*}, \mu^{*}\right)$ satisfies the following conditions:
(a) $\forall i \in N, \forall h \in H_{i}, \forall \gamma_{i} \in \Psi_{i}$,

$$
\pi_{i}\left(\gamma^{*} \mid \mu^{*}, h\right) \geq \pi_{i}\left(\gamma_{i}, \gamma_{-i}^{*} \mid \mu^{*}, h\right)
$$

(b) $\forall h \in H, \forall x \in h$,

$$
\mu^{*}(x)=\frac{\operatorname{Pr}\left(x \mid \gamma^{*}\right)}{\operatorname{Pr}\left(h \mid \gamma^{*}\right)}, \text { if } \operatorname{Pr}\left(h \mid \gamma^{*}\right)>0
$$

## (Weak) Perfect Bayesian and Sequential equilibrium (3/4)

Definition 2 Let $\gamma \in \Psi$ be a completely mixed behavioral strategy profile for game $\Gamma$ (that is, $\forall i \in N, \forall h \in H_{i}, \forall a \in A\left(h_{i}\right), \gamma_{i}(h)(a)>0$ ).

A corresponding assessment $(\mu, \gamma)$ is consistent if $\forall h \in H, \forall x \in h$ we have $\mu(x)=\frac{\operatorname{Pr}(x \mid \gamma)}{\operatorname{Pr}(h \mid \gamma)}$.

Definition 3 Let $\gamma \in \Psi$ be any behavioral strategy profile for game $\Gamma$ (not necessarily completely mixed).

A corresponding assessment $(\mu, \gamma)$ is consistent if it is the limit of a sequence of consistent assessments $\left\{\left(\mu_{k}, \gamma_{k}\right)\right\}_{k=1,2, \ldots}$ where $\gamma_{k}$ is completely mixed for all $k=1,2, \ldots$
(Weak) Perfect Bayesian and Sequential equilibrium (4/4)

Definition 4 A strategy profile $\gamma^{*}=\left(\gamma_{1}^{*}, \ldots, \gamma_{n}^{*}\right) \in \Psi$ is a sequential equilibrium of $\Gamma$ if there exists a system of beliefs $\mu^{*}$ such that:
a $\left(\gamma^{*}, \mu^{*}\right)$ is a consistent assessment
b $\forall i \in N, \forall h \in H_{i}, \forall \gamma_{i} \in \Psi_{i}$

$$
\pi_{i}\left(\gamma^{*} \mid \mu^{*}, h\right) \geq \pi_{i}\left(\gamma_{i}, \gamma_{-i}^{*} \mid \mu^{*}, h\right)
$$

This definition implies a sequential equilibrium is necessarily WPBE.

## WPBE and Sequential equilibria for examples

Game B of chapter 2.

$$
\pi_{2}(a \mid \mu, h)=2 \mu(A)+\mu(B)>\pi_{2}(b \mid \mu, h)=\mu(A)-2 \mu(B)
$$

Thus, by requirement (a) of WPBE, player 2 should play $a$ (independently of $\mu$, and the only best response of player 1 is to play $A$. ( $A, a$ ) is thus the only WPBE equilibrium, sustained by beliefs $\mu(A)=1$. There is another Nash equilibrium, which is also subgame-perfect $(F, b)$, but not WPBE.

The only WPBE is also sequential, for beliefs $\mu(A)=1$.
To see this, take a sequence putting probability ( $1 / k, 1-2 / k, 1 / k$ ) respectively on ( $F, A, B$ ) and ( $1-1 / k, 1 / k$ ) on $(a, b)$.
This sequence converges to ( $A, a$ ) and the beliefs associated to it, $\mu^{k}(A)=$ $\frac{1-2 / k}{1-1 / k}$. From this $\lim _{k \rightarrow \infty} \mu^{k}(A)=1$

## WPBE and Sequential equilibria for examples

(2/10)

Beer-Quiche.

There are no separating WPBE equilibria. That is, the Sender-player 1 cannot choose a different action in each information set.

To see this consider the situation where $\gamma_{s}^{*}(W)=B, \gamma_{s}^{*}(S)=Q$.

Then $\mu(W \mid B)=1, \mu(W \mid Q)=0$.
Thus, the best response of Receiver-player 2 is:
$\gamma_{r}^{*}(B)=D\left(\right.$ since $\left.\pi_{r}\left(D, \gamma_{s}^{*} \mid \mu, B\right)=1>\pi_{s}\left(N, \gamma_{s}^{*} \mid \mu, Q\right)=0\right)$
$\gamma_{r}^{*}(Q)=N\left(\right.$ since $\left.\pi_{r}\left(D, \gamma_{s}^{*} \mid \mu, Q\right)=0>\pi_{s}\left(N, \gamma_{s}^{*} \mid \mu, Q\right)=-1\right)$.
But then the Sender is not optimizing as
$\pi_{s}\left(B, \gamma_{r}^{*} \mid W\right)=0<\pi_{s}\left(Q, \gamma_{r}^{*} \mid W\right)=3$.

WPBE and Sequential equilibria for examples
$\qquad$ (3/10)

Now consider the situation where $\gamma_{s}^{*}(W)=Q, \gamma_{s}^{*}(S)=B$.

Then $\mu(W \mid B)=0, \mu(W \mid Q)=1$.
Thus, the best response of Receiver-player 2 is:
$\gamma_{r}^{*}(B)=N\left(\right.$ since $\left.\pi_{r}\left(D, \gamma_{s}^{*} \mid \mu, B\right)=-1<\pi_{s}\left(N, \gamma_{s}^{*} \mid \mu, Q\right)=0\right)$
$\gamma_{r}^{*}(Q)=D\left(\right.$ since $\left.\pi_{r}\left(D, \gamma_{s}^{*} \mid \mu, Q\right)=1>\pi_{s}\left(N, \gamma_{s}^{*} \mid \mu, Q\right)=0\right)$.
But then the Sender is not optimizing as
$\pi_{s}\left(Q, \gamma_{r}^{*} \mid W\right)=1<\pi_{s}\left(B, \gamma_{r}^{*} \mid W\right)=2$.

## WPBE and Sequential equilibria for examples

## (4/10)

There is a pooling WPBE equilibrium with $\gamma_{s}^{*}(W)=B, \gamma_{s}^{*}(S)=B$.
Then $\mu(W \mid B)=0.1$. Thus, the best response of Receiver is:
$\gamma_{r}^{*}(B)=N\left(\right.$ since $\left.\pi_{r}\left(N, \gamma_{s}^{*} \mid \mu, B\right)=0>\pi_{s}\left(D, \gamma_{s}^{*} \mid \mu, B\right)=1 * 0.1-1 * 0.9\right)$.
The response after $Q$ depends on beliefs
(since $\pi_{r}\left(N, \gamma_{s}^{*} \mid \mu, Q\right)=0$ and $\pi_{s}\left(D, \gamma_{s}^{*} \mid \mu, Q\right)=1 * \mu(W \mid Q)-1 * \mu(S \mid Q)$ ).
In order to show that a pooling equilibrium as above
we need beliefs such that the best response (by Receiver) is such that $B$ is optimal for both types of Sender.
One such response is if $\gamma_{r}^{*}(Q)=D$, since then
$\pi_{s}\left(Q, \gamma_{r}^{*} \mid W\right)=1<\pi_{s}\left(B, \gamma_{r}^{*} \mid W\right)=2$
and $\pi_{s}\left(Q, \gamma_{r}^{*} \mid S\right)=0<\pi_{s}\left(B, \gamma_{r}^{*} \mid S\right)=3$.
Some beliefs that would work are $\mu(W \mid Q)=1$,
as then $\pi_{r}\left(N, \gamma_{s}^{*} \mid \mu, Q\right)=0<\pi_{s}\left(D, \gamma_{s}^{*} \mid \mu, Q\right)=1$.
$\qquad$

## WPBE and Sequential equilibria for examples

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There is a pooling equilibrium with $\gamma_{s}^{*}(W)=B, \gamma_{s}^{*}(S)=Q$.
Then $\mu(W \mid Q)=0.1$. Thus, the best response of Receiver-player 2 is:
$\gamma_{r}^{*}(Q)=N\left(\right.$ since $\left.\pi_{r}\left(N, \gamma_{s}^{*} \mid \mu, Q\right)=0>\pi_{s}\left(D, \gamma_{s}^{*} \mid \mu, Q\right)=1 * 0.1-1 * 0.9\right)$.
The response after $B$ depends on beliefs
(since $\pi_{r}\left(N, \gamma_{s}^{*} \mid \mu, B\right)=0$ and $\pi_{s}\left(D, \gamma_{s}^{*} \mid \mu, B\right)=1 * \mu(W \mid B)-1 * \mu(S \mid B)$ ).
In order to show that there is a pooling equilibrium as above we need beliefs such that the best response (by Receiver) is such that $Q$ is optimal for both types of Sender.
One such response is if $\gamma_{r}^{*}(B)=D$, since then $\pi_{s}\left(B, \gamma_{r}^{*} \mid W\right)=0<\pi_{s}\left(Q, \gamma_{r}^{*} \mid W\right)=3$ and $\pi_{s}\left(B, \gamma_{r}^{*} \mid S\right)=1<\pi_{s}\left(Q, \gamma_{r}^{*} \mid S\right)=2$.

Some beliefs that would work are $\mu(W \mid B)=1$, as then $\pi_{r}\left(N, \gamma_{s}^{*} \mid \mu, B\right)=0<\pi_{s}\left(D, \gamma_{s}^{*} \mid \mu, B\right)=1$.
$\qquad$

## WPBE and Sequential equilibria for examples

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## Game with WPBE not sequential

$(A, b, U)$ is a WPBE equilibrium, as long as $\mu(a) \geq 2 * \mu(b)=2 *(1-\mu(a))$.

Notice that under that condition, this equilibrium satisfies the requirement (a) of the definition, since $\pi_{1}\left(A, \gamma_{-1}\right)=1>\pi_{1}\left(B, \gamma_{-1}\right)=0, \pi_{1}\left(A, \gamma_{-1}\right)=1>\pi_{1}\left(C, \gamma_{-1}\right)=0$, and $\pi_{2}\left(a, \gamma_{-2} \mid \mu\right)=\mu(B) * 0+\mu(C) * 0 \leq \pi_{2}\left(b, \gamma_{-2} \mid \mu\right)=\mu(B) * 0+\mu(C) * 1$ and $\pi_{3}\left(U, \gamma_{-3} \mid \mu\right)=\mu(a) * 1+\mu(b) * 0 \geq \pi_{3}\left(V, \gamma_{-3} \mid \mu\right)=\mu(a) * 0+\mu(b) * 2$ (since $\mu(a) \geq 2 * \mu(b)$ ).

These beliefs also satisfy requirement (b) because given $\gamma_{1}(A)=1$ any beliefs satisfy the definition.

## WPBE and Sequential equilibria for examples

( $A, b, U$ ) is NOT a sequential equilibrium. The reason is that beliefs with $\mu(a) \geq 2 * \mu(b)=2 *(1-\mu(a))$
cannot be part of a consistent assessment.

Let any beliefs $\mu(a), \mu(b)$ be part of a consistent assessment where $\gamma=(A, b, U)$.
Let also $\left(\gamma_{1}^{k}, \gamma_{2}^{k}, \gamma_{3}^{k}\right)$, be the sequence that converges to $\gamma$. Then, in a consistent assessment

$$
\mu^{k}(a)=\frac{\gamma_{1}^{k}(B) * \gamma_{2}^{k}(a)}{\gamma_{1}^{k}(B) * \gamma_{2}^{k}(a)+\gamma_{1}^{k}(B) * \gamma_{2}^{k}(b)}=\frac{\gamma_{2}^{k}(a)}{\gamma_{2}^{k}(a)+\gamma_{2}^{k}(b)}=\gamma_{2}^{k}(a) ;
$$

and $\mu^{k}(b)=\gamma_{2}^{k}(b)$.Thus, since we know that $\lim _{k \rightarrow \infty} \gamma_{2}^{k}(a)=0$ we must have in a consistent assessment that $\mu(a)=0<2(1-\mu(a))$.

## WPBE and Sequential equilibria for examples

(8/10)
Spence education model (Osborne and Rubinstein's version).

Pooling equilibrium. $e_{L}=e_{H}=e^{*}$.
In this case, necessarily, $\mu\left(\theta^{H} \mid e^{*}\right)=p^{H}$, thus $w\left(e^{*}\right)=p^{H} \theta^{H}+p^{L} \theta^{L}$. For this to be an equilibrium we need that for all alternative $e$, $w(e)-e / \theta^{i} \leq w\left(e^{*}\right)-e^{*} / \theta^{i}$ for $i=H, L$.

The easiest way to achieve this is if the firm believes that all deviations come from $\theta^{L}$. Thus $\mu\left(\theta^{H} \mid e\right)=0$, and $w(e)=\theta^{L}$ if $e \neq e^{*}$.
Thus, best possible deviation is if $e=0$
(the salary is equal for all $e \neq e^{*}$ and the cost is lowest at $e=0$.) Then $w(0) \leq w\left(e^{*}\right)-e^{*} / \theta^{i}$ or $i=H, L$ if $\theta^{L} \leq p^{H} \theta^{H}+p^{L} \theta^{L}-e^{*} / \theta^{L}$, that is, if $e^{*} \leq \theta^{L} p^{H}\left(\theta^{H}-\theta^{L}\right)$.

## WPBE and Sequential equilibria for examples

$\qquad$
(9/10)
Separating equilibrium. $e_{L}=0 \neq e_{H}=e^{*}$.
In this case, we must have necessarily $e_{L}=0$.
Suppose not. Then $e_{L}>0$. In as separating equilibrium $w\left(e_{L}\right)=\theta^{L}$. Furthermore, the wage for $w(0)=\mu\left(\theta^{H} \mid 0\right) \theta^{H}+\mu\left(\theta^{L} \mid 0\right) \theta^{L} \geq \theta^{L}$. But the cost of education is 0 , so that the payoff under $e=0$ is $\theta^{L}$, whereas under $e_{L}$ it is $\theta^{L}-e_{L}<\theta^{L}$, a contradiction.

In order for neither worker wanting to choose a different $e$, it is easiest to assume $\mu\left(\theta^{H} \mid e\right)=0$ if $e \neq e^{*}$.

Then, the best possible deviation for $\theta^{H}$ is $e=0$
(same wage and more cost otherwise) and the best possible deviation for $\theta^{L}$ is $e^{*}$ (same wage as with $e=0$ and more cost otherwise).

## WPBE and Sequential equilibria for examples

To have that $e_{L}=0 \neq e_{H}=e^{*}$ are optimal now only requires that:

$$
\theta^{L} \geq \theta^{H}-e^{*} / \theta^{L} \text { and } \theta^{L} \leq \theta^{H}-e^{*} / \theta^{H}
$$

This is equivalent to

$$
\left(\theta^{H}-\theta^{L}\right) \theta^{H} \geq e^{*} \geq\left(\theta^{H}-\theta^{L}\right) \theta^{L}
$$

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