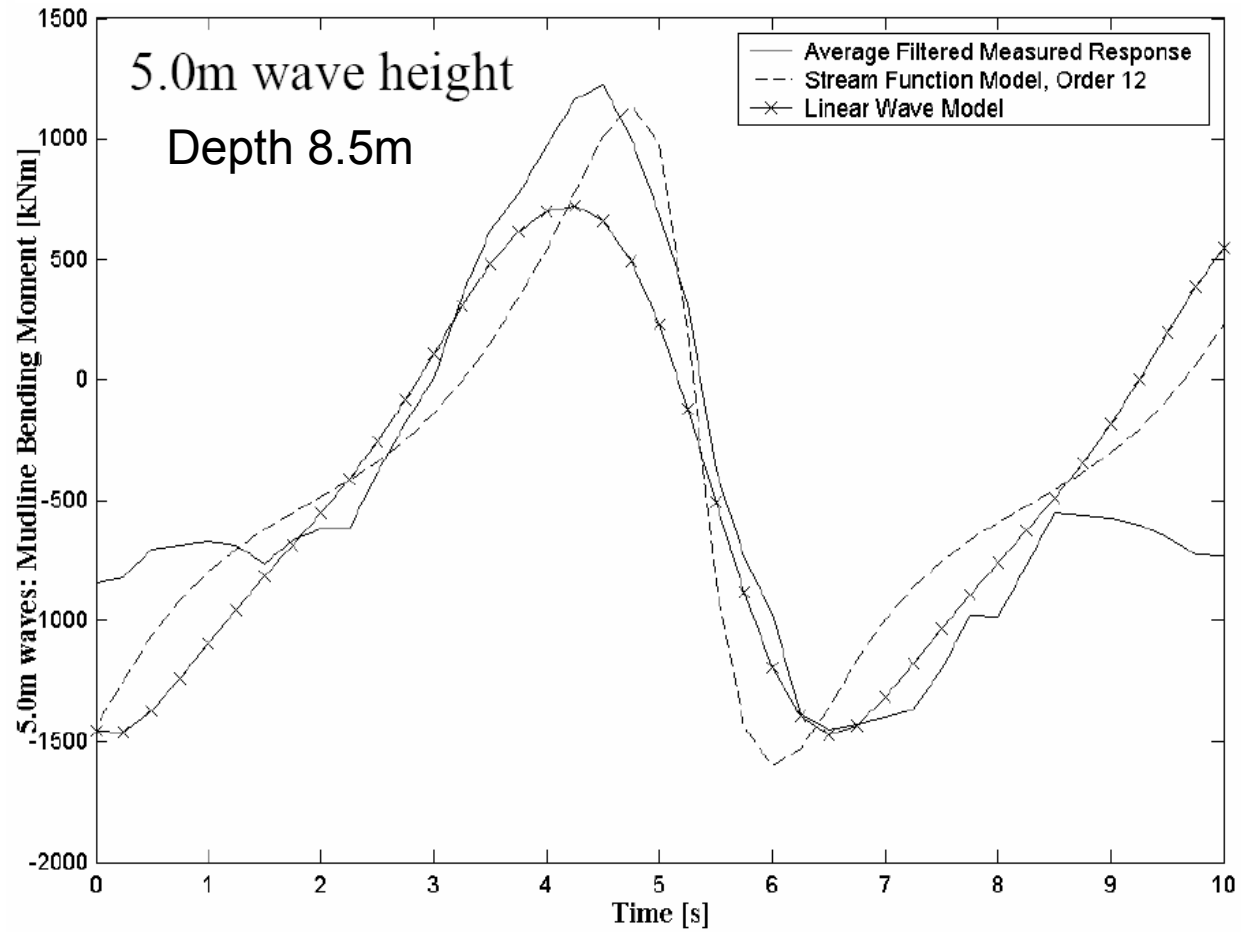
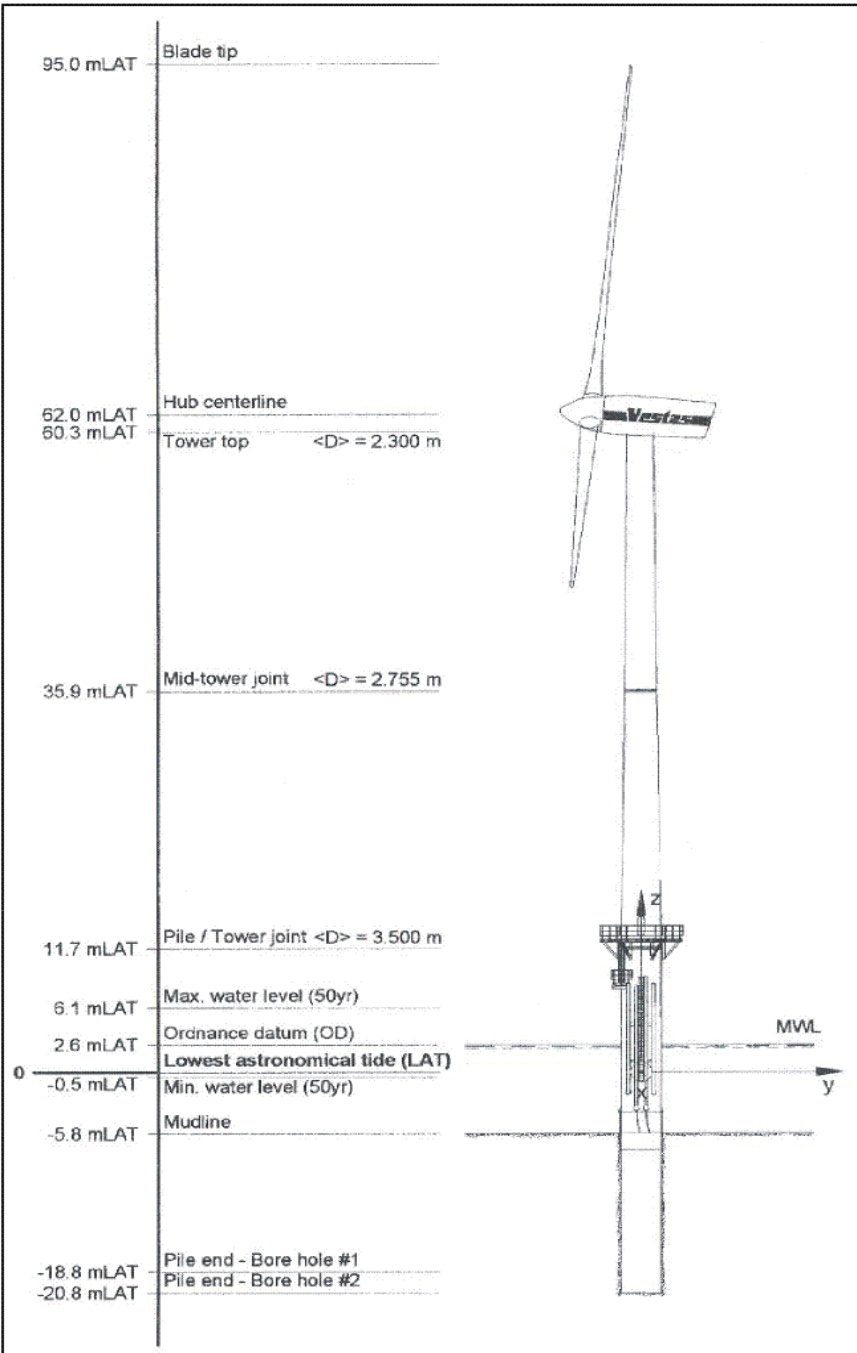


Wave and Current Loads on Offshore Structures

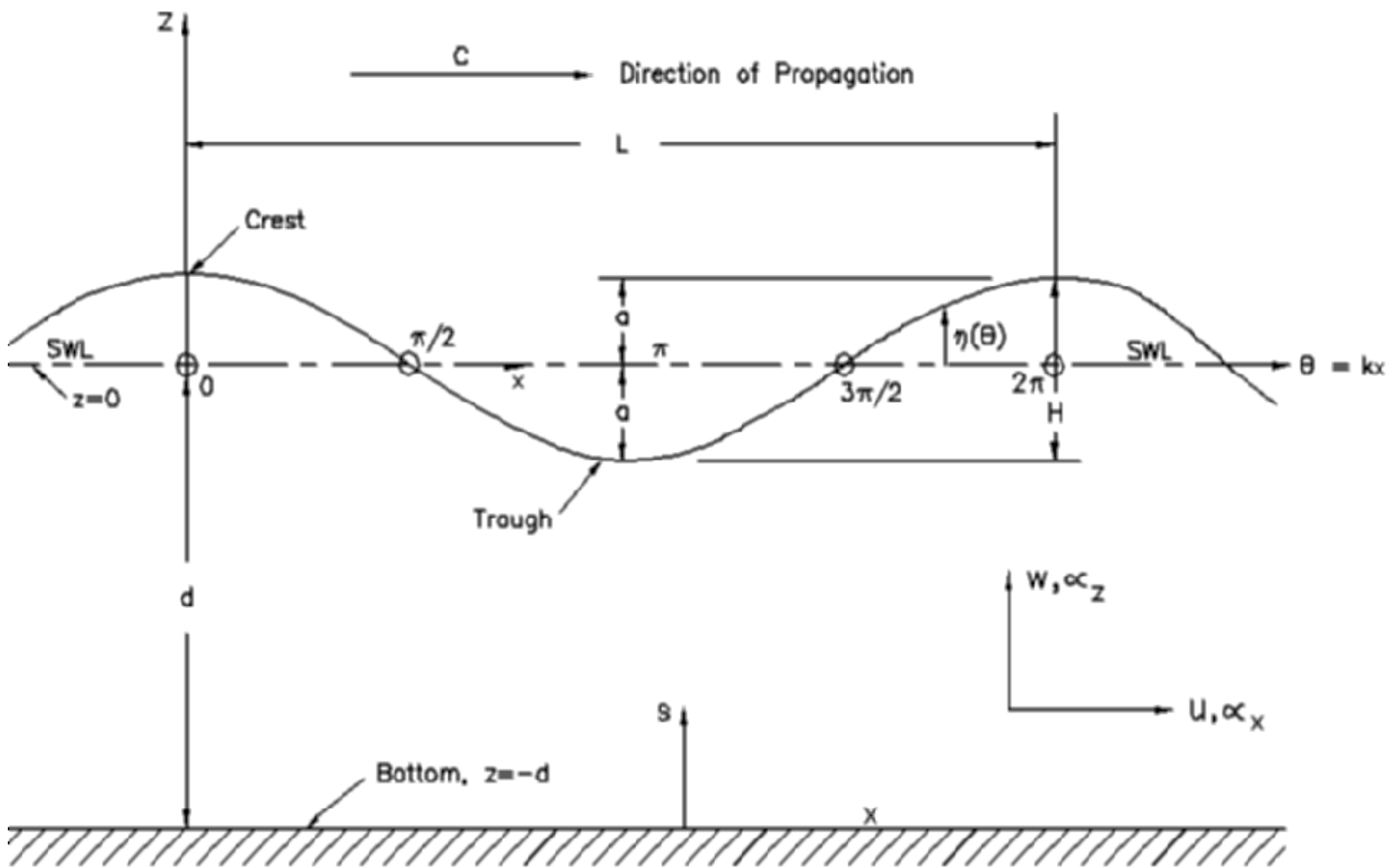
A photograph of an offshore wind farm at sunset. The sky is a mix of orange, yellow, and grey. Several wind turbines are visible, with the central one being the largest and most prominent. The sea is dark and turbulent, with large white-capped waves crashing in the foreground. The turbines have yellow bases and white towers.

Application of Morison Equation

Wave Load Example



Wave Parameters

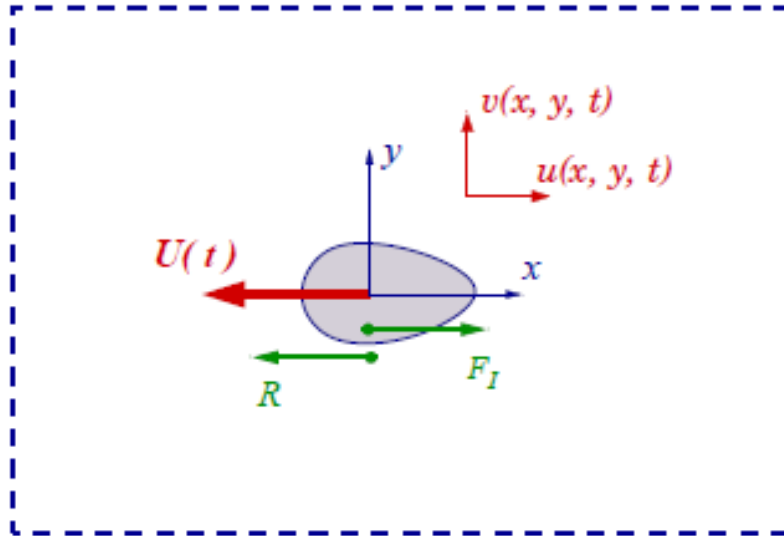


Wave Parameters

Relative Depth	Shallow Water $\frac{d}{L} < \frac{1}{25}$	Transitional Water $\frac{1}{25} < \frac{d}{L} < \frac{1}{2}$	Deep Water $\frac{d}{L} < \frac{1}{2}$
1. Wave profile	Same As >	$\eta = \frac{H}{2} \cos \left[\frac{2\pi x}{L} - \frac{2\pi t}{T} \right] = \frac{H}{2} \cos \theta$	< Same As
2. Wave celerity	$C = \frac{L}{T} = \sqrt{gd}$	$C = \frac{L}{T} = \frac{gT}{2\pi} \tanh \left(\frac{2\pi d}{L} \right)$	$C = C_0 = \frac{L}{T} = \frac{gT}{2\pi}$
3. Wavelength	$L = T\sqrt{gd} = CT$	$L = \frac{gT^2}{2\pi} \tanh \left(\frac{2\pi d}{L} \right)$	$L = L_0 = \frac{gT^2}{2\pi} = C_0 T$
4. Group velocity	$C_g = C = \sqrt{gd}$	$C_g = nC = \frac{1}{2} \left[1 + \frac{4\pi d/L}{\sinh(4\pi d/L)} \right] C$	$C_g = \frac{1}{2} C = \frac{gT}{4\pi}$
5. Water particle velocity			
(a) Horizontal	$u = \frac{H}{2} \sqrt{\frac{g}{d}} \cos \theta$	$u = \frac{H}{2} \frac{gT}{L} \frac{\cosh[2\pi(z+d)/L]}{\cosh(2\pi d/L)} \cos \theta$	$u = \frac{\pi H}{T} e^{\left(\frac{2\pi z}{L}\right)} \cos \theta$
(b) Vertical	$w = \frac{H\pi}{T} \left(1 + \frac{z}{d} \right) \sin \theta$	$w = \frac{H}{2} \frac{gT}{L} \frac{\sinh[2\pi(z+d)/L]}{\cosh(2\pi d/L)} \sin \theta$	$w = \frac{\pi H}{T} e^{\left(\frac{2\pi z}{L}\right)} \sin \theta$

Added Mass and Inertial Forces

Body moves in an inviscid fluid with speed $U < 0$:



- Fluid velocity (u, v) is proportional to body velocity U
- Mass of moving fluid is proportional to fluid density ρ and body volume V
- Average fluid velocity is opposite to U
- Fluid does not move far away from the body

Momentum: $I(t) = -c_m \rho V U(t)$ where c_m depends on body shape

Steady motion: $I = const \Rightarrow R = 0$

Unsteady motion: $R = dI/dt = -c_m \rho V dU/dt$

Inertial force on an accelerating body:

$$F_I = c_m \rho V \frac{dU}{dt} = m_a \frac{dU}{dt}$$

ADDED MASS: $m_a = c_m \rho V$; c_m - ADDED MASS COEFFICIENT

Morison Equation

MORISON'S EQUATION: calculates force applied to a body by an uniform unsteady flow

$$D(t) = \frac{1}{2} C_D A \rho U(t) |U(t)| + C_M V \rho \frac{dU(t)}{dt}$$

V, A – volume and cross section area of the body;

C_D – drag coefficient;

$C_M = c_m + 1$ – inertial force coefficient, where "1" accounts for a hydrostatic force component in accelerated fluid

Task: | Prove that $C_M = c_m + 1$

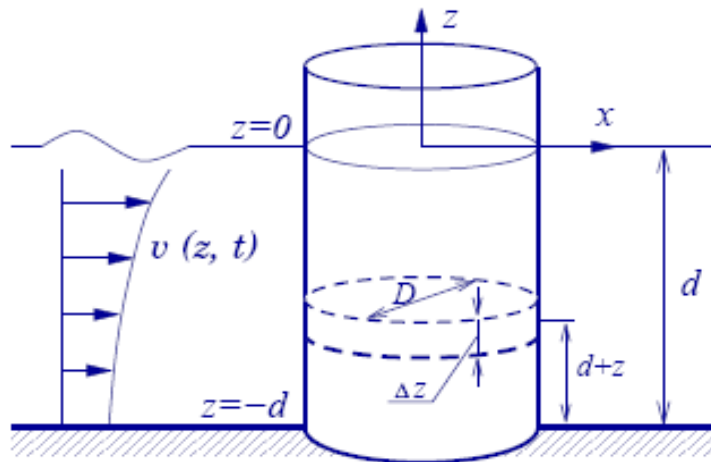
- Typical values of coefficients for a cylinder: $C_D = 1; C_M = 2$

Application to Wave Loads

Deep water:

$$v_x = a \frac{g k}{\omega} \frac{\cosh(k(z+d))}{\cosh(kd)} \cos(kx - \omega t); \quad \omega = \sqrt{kg \tanh(kd)}; \quad k = 2\pi/\lambda$$

a – wave amplitude, g – gravity, k – wave number, λ – wave length, ω – frequency

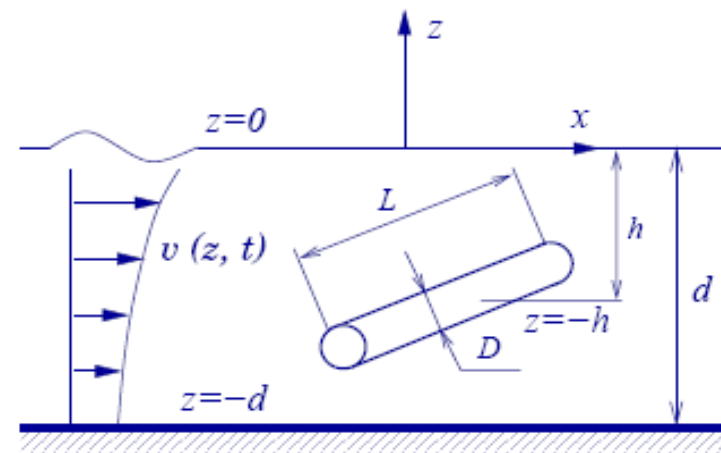


Vertical column:

$$dA = D dz; \quad dV = \pi D^2 dz/4;$$

$$U = v(z, t)$$

Integration from $z = -h$ to $z = 0$



Horizontal element:

$$A = DL; \quad V = \pi D^2 L/4;$$

$$U = v(-h, t)$$

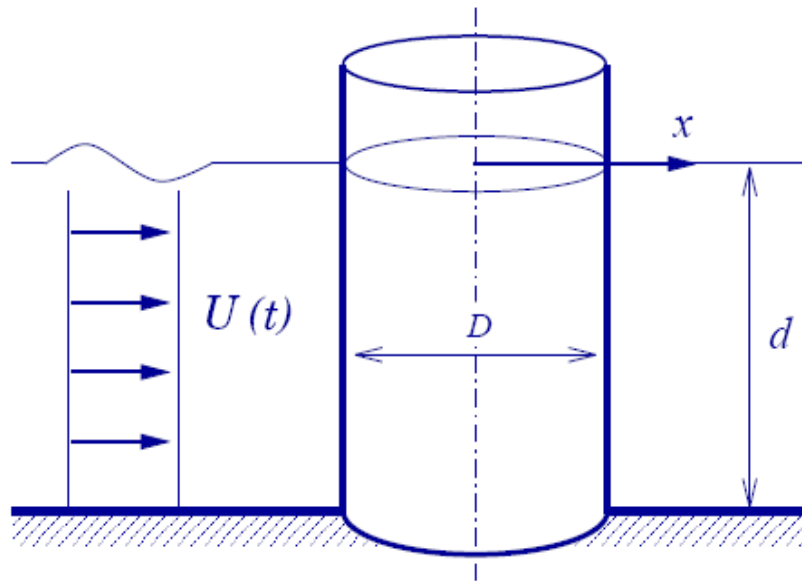
Local parameters, no integration

Application to Wave Loads

Shallow water ($\lambda > 20 d$):

$$U(t) = a \sqrt{\frac{g}{d}} \cos(kx - \omega t); \quad k = 2\pi/\lambda; \quad \omega = k \sqrt{gd},$$

a – wave amplitude, g – gravity, k – wave number, λ – wave length, ω – frequency



Velocity does not change with depth

$$A = D d; \quad V = \pi D^2 d/4;$$

$$U = U(t)$$

APPLICABILITY:

Morison's equation can be applied to waves when $D \ll \lambda$ and flow can be considered as locally uniform

Problem

Horizontal velocity component of a wave propagating in x -direction in water of constant depth d is described by the equation

$$v_x = \frac{a g k}{\omega} \frac{\cosh(k(z+d))}{\cosh(kd)} \cos(kx - \omega t),$$

where a is wave amplitude, g is gravity acceleration, $k = 2\pi/\lambda$ is wave number, λ is wave length, $\omega = \sqrt{k g \tanh(kd)}$ is frequency of the wave, $z = 0$ and $z = -d$ represent water surface and bottom respectively. A vertical cylindrical oil rig column of 10 m in diameter is placed in 50 m deep water. Calculate the maximal horizontal force and the moment about the bottom mounting applied to the column by a 200 m long wave of 3 m amplitude. The values of drag coefficient and inertial coefficient are $C_D = 1$ and $C_M = 2$. Discuss the applicability of your solution.

Reading

Chakrabarti, Subrata (2005). Handbook of Offshore Engineering, Volumes 1-2. Elsevier.

4. Loads and Responses

4.1 Introduction

4.2 Gravity Loads

4.3 Hydrostatic Loads

4.4 Resistance Loads

4.5 Current Loads on Structures

4.7 Wave Loads on Structures

4.7.1 Morison Equation

4.7.2 Forces on Oscillating Structures

4.7.3 Wave Plus Current Loads

4.7.4 Design Values for Hydrodynamic Coefficients

Online version available at:

<http://app.knovel.com/hotlink/toc/id:kpHOEV0001/handbook-offshore-engineering>

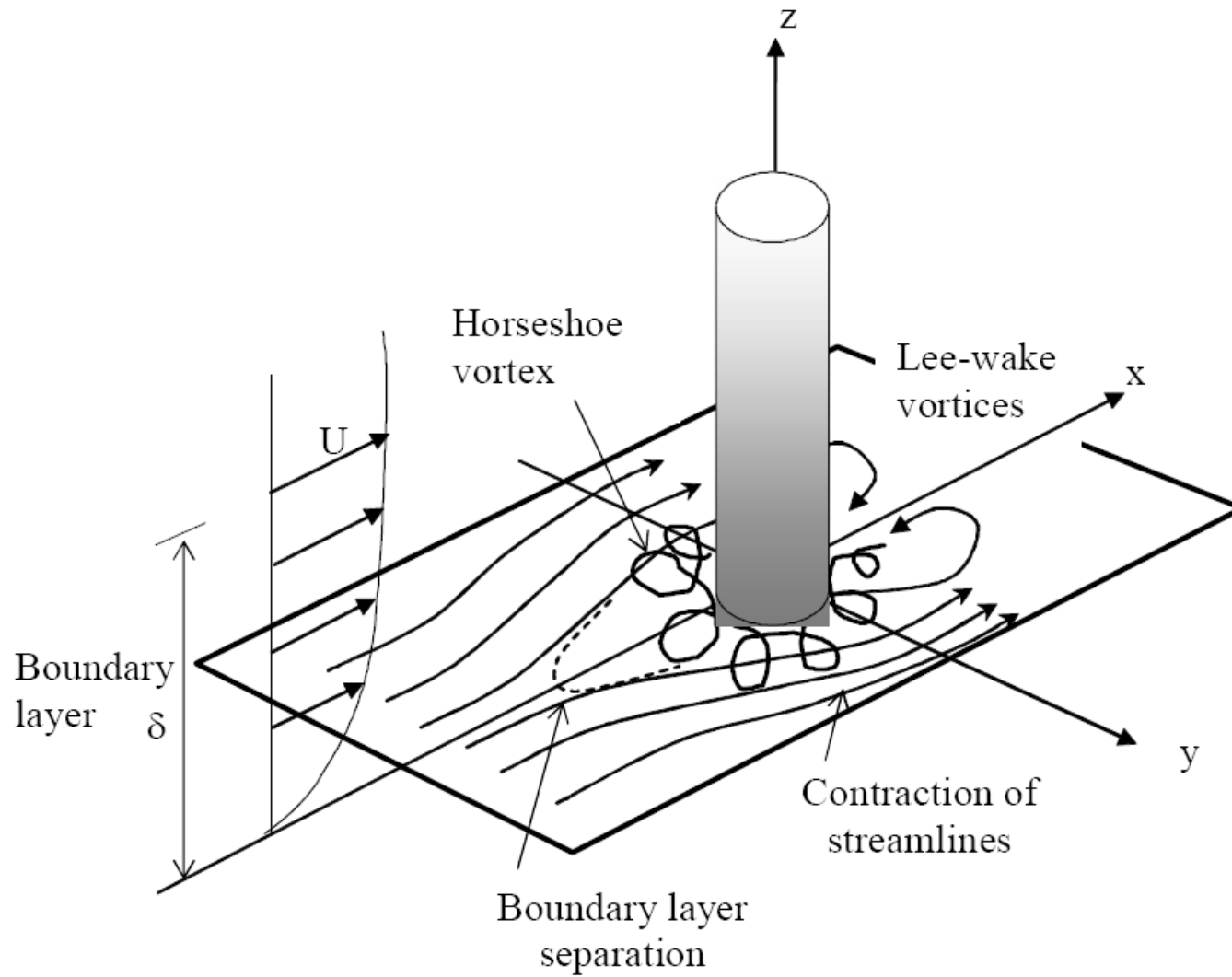
Sorensen, John D. Sorensen, Jens N. (2011). Wind Energy Systems - Optimising Design and Construction for Safe and Reliable Operation. Woodhead Publishing.

15 Offshore environmental loads and wind turbine design:
impact of wind, wave, currents and ice

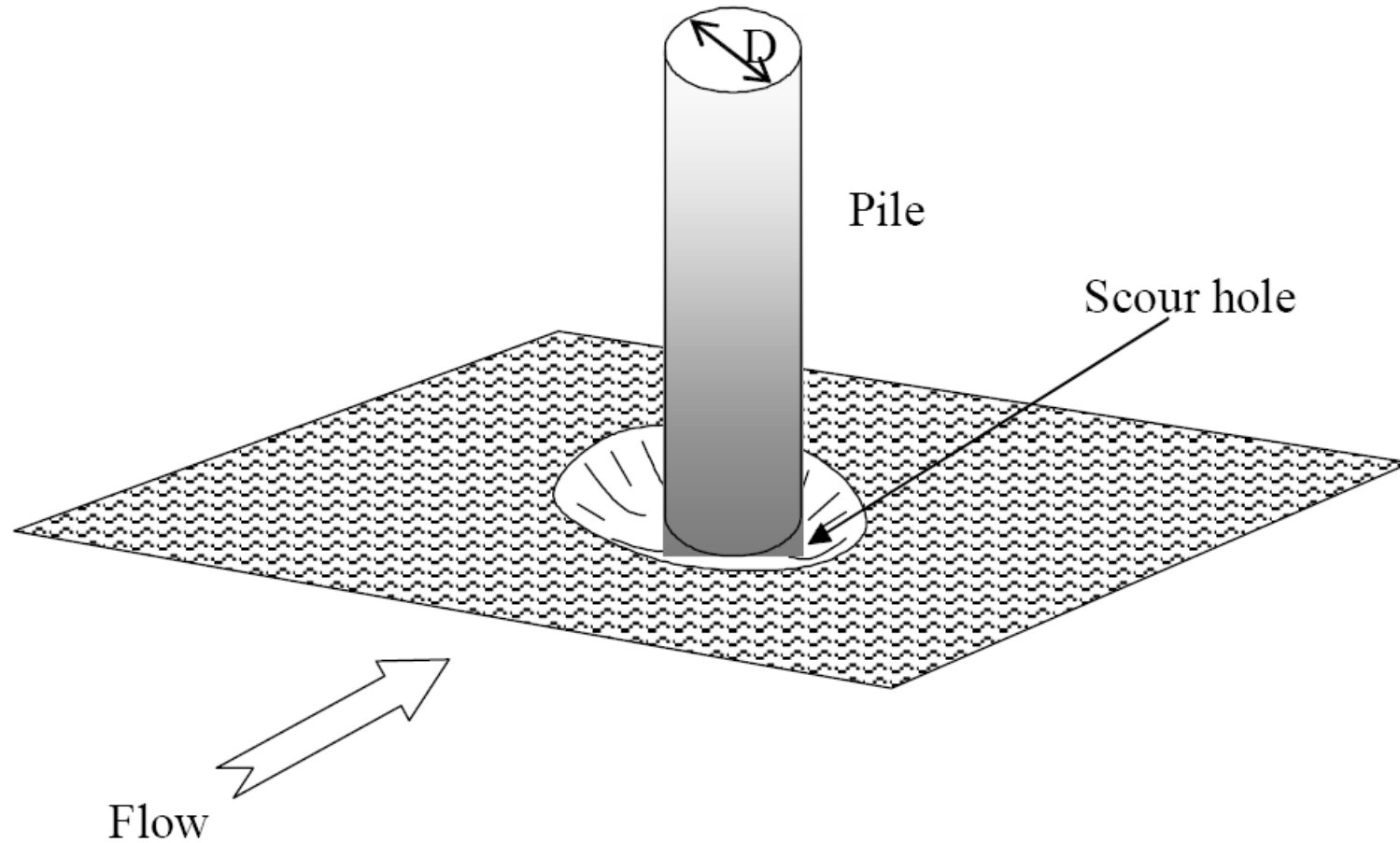
Online version available at:

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A Note on Scour



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