

Example of Application of Morrison Equation

5. Horizontal velocity component of a wave propagating in x -direction in water of constant depth d is described by the equation

$$v_x = \frac{a g k}{\omega} \frac{\cosh(k(z+d))}{\cosh(kd)} \cos(kx - \omega t),$$

where a is wave amplitude, g is gravity acceleration, $k = 2\pi/\lambda$ is wave number, λ is wave length, $\omega = \sqrt{k g \tanh(kd)}$ is frequency of the wave, $z = 0$ and $z = -d$ represent water surface and bottom respectively. A vertical cylindrical oil rig column of 10 m in diameter is placed in 50 m deep water. Calculate the maximal horizontal force and the moment about the bottom mounting applied to the column by a 200 m long wave of 3 m amplitude. The values of drag coefficient and inertial coefficient are $C_D = 1$ and $C_M = 2$. Discuss the applicability of your solution.

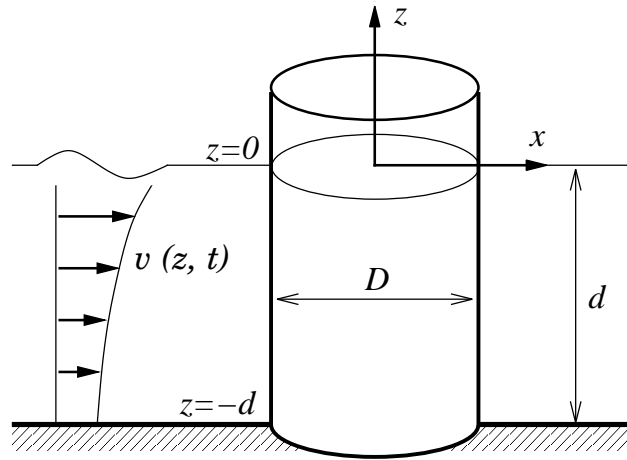


Fig. 5.1

Solution:

For a given position ($x = 0$) the horizontal velocity in the wave can be written as the product of a function of t , a function of z and a constant

$$v = U \cosh(k(z+d)) \cos(\omega t), \quad (1)$$

where the constant U represents the maximal velocity at the bottom ($z = -d$) and can be calculated using the problem data

$$U = \frac{a g k}{\omega \cosh(kd)}.$$

Force dF on a small column element of thickness dz (Fig. 5.2) can be calculated by using Morrison's equation (*What assumptions justify its application?*)

$$dF = \frac{1}{2} C_D \rho D v |v| dz + C_M \rho \frac{\pi D^2}{4} \dot{v} dz. \quad (2)$$

Using (1) each term (2) can be represented as the product of a function of time, a function of z and a constant

$$dF = K_D \cos(\omega t) |\cos(\omega t)| \cosh^2(k(z+d)) dz - K_I \sin(\omega t) \cosh(k(z+d)) dz,$$

where the constants

$$K_D = \frac{1}{2} C_D \rho D U^2; \quad K_I = C_M \rho \frac{\pi D^2}{4} U$$

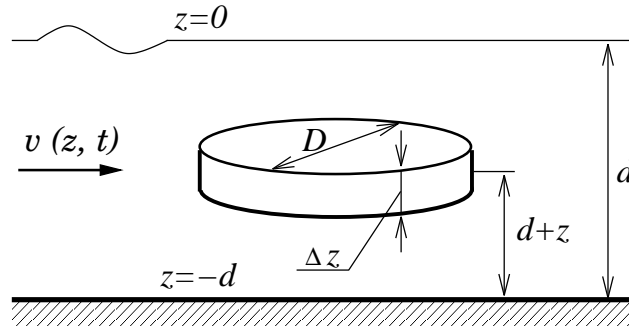


Fig. 5.2

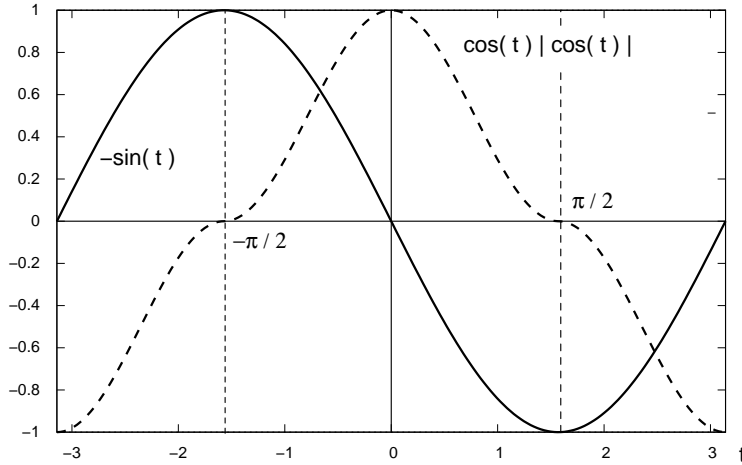


Fig. 5.3

can be calculated using the problem data. The corresponding overturning moment about the base can be obtained by multiplying dF by the distance to the base $z + d$

$$dM = K_D \cos(\omega t) |\cos(\omega t)| \cosh^2(k(z+d))(z+d) dz - K_I \sin(\omega t) \cosh(k(z+d))(z+d) dz,$$

To calculate the total force and moment we have to integrate dF and dM from the bottom $z = -d$ to the surface $z = 0$. This implies taking the following integrals

$$I_1 = \int_{-d}^0 \cosh^2(k(z+d)) dz; \quad I_2 = \int_{-d}^0 \cosh(k(z+d)) dz;$$

$$I_3 = \int_{-d}^0 \cosh^2(k(z+d))(z+d) dz; \quad I_4 = \int_{-d}^0 \cosh(k(z+d))(z+d) dz.$$

The values of the integrals for the particular values of d and k can be estimated numerically, for example using Excel (e.g. see 1st year Cylinder lab), or by using analytical methods and integral tables (refer to your math course). The following formulas are valid for the integrals I_1 - I_4

$$I_1 = \frac{2kd + \sinh(2kd)}{4k}; \quad I_2 = \frac{\sinh(kd)}{k};$$

$$I_3 = \frac{1 + 2(kd)^2 - \cosh(2kd) + 2kd \sinh(2kd)}{8k^2}; \quad I_4 = \frac{1 - \cosh kd + kd \sinh(kd)}{k^2},$$

and their values can be calculated using the problem data.

Now we have the force and overturning moment as functions of time

$$F(t) = K_D I_1 \cos(\omega t) |\cos(\omega t)| - K_I I_2 \sin(\omega t);$$

$$M(t) = K_D I_3 \cos(\omega t) |\cos(\omega t)| - K_I I_4 \sin(\omega t)$$

and our task is to find their maximal values. From Fig. 5.3 it is clear that the maximum occurs when both terms in expressions for $F(t)$ and $M(t)$ are positive, that is when $-\pi/2 < \omega t < 0$. It is convenient to apply a phase shift $\omega t \rightarrow \omega t + \pi/2$ and consider the interval $0 < \omega t < \pi/2$. We can write then

$$\begin{aligned} F(t) &= K_D I_1 \sin^2(\omega t) + K_I I_2 \cos(\omega t); \\ M(t) &= K_D I_3 \sin^2(\omega t) + K_I I_4 \cos(\omega t) \end{aligned} \quad (3)$$

and maxima occur when time derivatives are 0.

Force:

$$\dot{F} = 2\omega K_D I_1 \sin(\omega t) \cos(\omega t) - \omega K_I I_2 \sin(\omega t) = \omega \sin(\omega t) (2K_D I_1 \cos(\omega t) - K_I I_2) = 0,$$

which happens when either

$$\omega t = 0 \quad \text{or} \quad \omega t = \arccos\left(\frac{K_I I_2}{2K_D I_1}\right).$$

To calculate the value of the force maximum substitute these values of ωt to the first equation of (3) and select the maximal value. Note that when $K_I I_2 > 2K_D I_1$ arccos does not exist. The force maximum then occurs at $t = 0$ and equals to the inertial force component $K_I I_2$.

Similarly, the moment maximum occurs when

$$\omega t = 0 \quad \text{or} \quad \omega t = \arccos\left(\frac{K_I I_4}{2K_D I_3}\right).$$