

① The Keldysh parameter is given by $\gamma = \sqrt{I_p / 2U_p}$ where I_p is the ionization potential and U_p the ponderomotive energy (the mean quiver energy of an electron in a field).

① This parameter delimits the tunneling regime and the multiphoton regime. In the tunneling regime ($\gamma < 1$), the electron reaches the continuum by tunnel ionization.

④ In this case, the external field is assumed to be quasi-static and the electron tunnels through the potential barrier $V_{eff} = V(r) - \vec{r} \cdot \vec{E}(t)$. In this regime, intermediate resonances are not important.

② This corresponds to high driving field intensities and/or low frequencies.

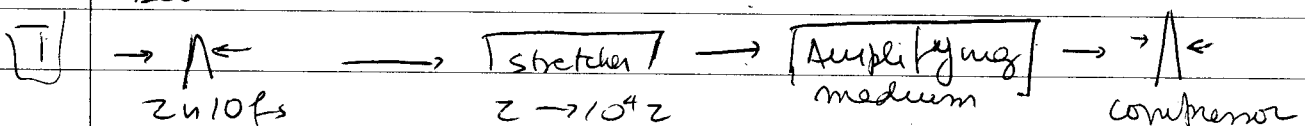
② In the multiphoton regime ($\gamma > 1$), the electron reaches the continuum by a multiphoton transition. The atom is being driven too quickly by the field for tunneling to occur. In this case, atom-laser resonances play an important role. This corresponds to not so high driving-field intensities and/or high frequencies.

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② Chirped pulse amplification

① (a) In chirped pulse amplification, a short laser pulse is stretched, amplified and then compressed again. The stretcher is built employing lenses and/or diffraction gratings in such a way that the "red" and "blue" components of the pulse are separated i.e., a chirp is introduced in the pulse.

A Schematic representation of this process is provided below



(b) Chirped pulse amplification made it possible to overcome an important obstacle to high-intensity laser fields: self focusing. Self focusing is caused by the fact that:

[I] (i) the beam profile varies in the direction perpendicular to the propagation direction

[I] (ii) The active medium has an intensity dependent refractive index $n = n_0 + n_1 I + n_2 I^2 + \dots$

[I] Hence, the center and the edges of the active material exhibit different refractive indices, and it behaves like a lens. This leads to the distortion of the pulse and

[I] to the destruction of the material. By stretching the pulse so that it carries the same energy but has a

[I] lower intensity, one reduces the effects caused by self-focusing and allows light amplification.

[3] (c) Ideally, at the end of the process the spectral distribution of the pulse should be equal to that it had before being ~~stretched~~ stretched. This means that the chirp introduced by the stretcher should be compensated by the compressor. In reality, the residual chirp must be minimized.

(3)

The Zeeman Tuning Technique

Given: Average radiation pressure force on a two-level atom

$$F = - \frac{\hbar \Omega^2 \Gamma k}{\Gamma^2 + 2\Omega^2 + 4[\omega - \omega_0 + kv]^2} \quad (*)$$

(a) The inhomogeneous magnetic field will shift the transition frequency by $\gamma B(z)$ (hint.)

[1] Hence $\omega - \omega_0 + kv \rightarrow \omega - \omega_0 - \gamma B(z) + kv$ in (*)

[1] F is maximal if $\omega - \omega_0 - \gamma B(z) + kv = 0$ (1)
This gives the constant acceleration

[1]
$$a_{\max} = \frac{F_{\max}}{M} = \frac{\hbar k}{M} \frac{\Omega^2 \Gamma}{\Gamma^2 + 2\Omega^2}$$

[2] • Low laser intensity: $\Omega \ll \Gamma \Rightarrow$ the acceleration is proportional to Ω^2 and thus increases linearly with the intensity

[2] • High laser intensity: $\Omega \gg \Gamma$: $a_{\max}$ saturates to $a_s = \frac{\hbar k}{M} \frac{\Gamma}{2}$. Hence, it cannot increase

indefinitely

(7)

(b) Integrating $a_{\max}$ twice in time we find

[2]
$$v = v_0 + a_{\max} t \quad (2)$$

$$z = v_0 t + \frac{a_{\max} t^2}{2} \quad (3)$$

We want, however, v as a function of z . Hence we must eliminate t .

From (3)
$$\frac{a_{\max} t^2}{2} + v_0 t - z = 0$$

$$t = -\frac{v_0}{a_{\max}} \pm \frac{1}{a_{\max}} \sqrt{v_0^2 + 2a_{\max}z}$$

Inserting into (2),

$$v = v_0 + a_{\max} \left[-\frac{v_0}{a_{\max}} \pm \frac{1}{a_{\max}} \sqrt{v_0^2 + 2a_{\max}z} \right]$$

$$\Rightarrow v = \pm \sqrt{v_0^2 + 2a_{\max}z}$$

We will consider only the positive root as the negative root implies a change in the direction of motion

This gives
$$v = \sqrt{\frac{v_0^2 - \hbar \Omega^2 k z}{M(\Gamma^2 + 2\Omega^2)}}$$

Note that, for v to be real, the term inside the square root must be positive. Hence,

$$v_0^2 \geq \frac{\hbar \Omega^2 k z}{M(\Gamma^2 + 2\Omega^2)}$$

$$\Rightarrow z_{\max} = \frac{(\Gamma^2 + 2\Omega^2) M v_0^2}{\Omega^2 \hbar k}$$

This implies that there is an upper bound on z , which will depend on the initial ~~velocity~~ kinetic energy of the atom considered

To encounter the shape of the field we will use

$$(1) \Rightarrow B(z) = \frac{1}{\gamma} \left[\Delta + k \sqrt{v_0^2 + 2a_{\max}z} \right]$$

- [1] Physically, apart from making the atom always resonant with the decelerating field, $B(z)$ guarantees a maximal, constant deceleration.

(10)

① Optical molasses

- [1] (a) F_{z1} is related to the co-propagating beam and F_{z2} to the counter-propagating beam. This can be seen by inspection of the general expression for the radiation pressure force. Since the Doppler term is $\vec{k} \cdot \vec{v}$, a positive or negative sign indicates that $\vec{k}$ and $\vec{v}$ are in the opposite, or in the same direction, respectively.

(3)

- [1] (b) Small velocities: $k v_z \ll \Delta$

Hence, we will write

$$F_{zn} = \frac{\hbar \Gamma}{\underbrace{\Gamma^2 + 2\Omega^2}_a + \underbrace{4\Delta^2}_b \left[\underbrace{1 \pm \frac{k v_z}{\Delta}}_x \right]^2} \quad (*)$$

- [1] Expansion in series of (*)

[2] $F_{z1} \approx \frac{1}{a+b} - \frac{2bx}{(a+b)^2} + \frac{(-ab+3b^2)x^2}{(a+b)^3} + O(x^3) + \dots$

[2] $F_{z2} \approx \frac{1}{a+b} + \frac{2bx}{(a+b)^2} + \frac{(-ab+3b^2)x^2}{(a+b)^3} + O(x^3) + \dots$

Cumbersome if done by hand; give 2 marks each depending on the effort. $\uparrow_{\text{upto}}$

[1] $F_{z1} - F_{z2} = \frac{4bx}{(a+b)^2} + O(x^3)$ (even ^{powers} cancel out)

[1]

$$F_z \propto \frac{\hbar \Delta k \Gamma}{[\Gamma^2 + 2\Delta^2 + 4\Delta^2]}$$

[2]

This force is linearly dependent on the velocity, and it is viscous for red-detuned laser beams ($\Delta < 0$)

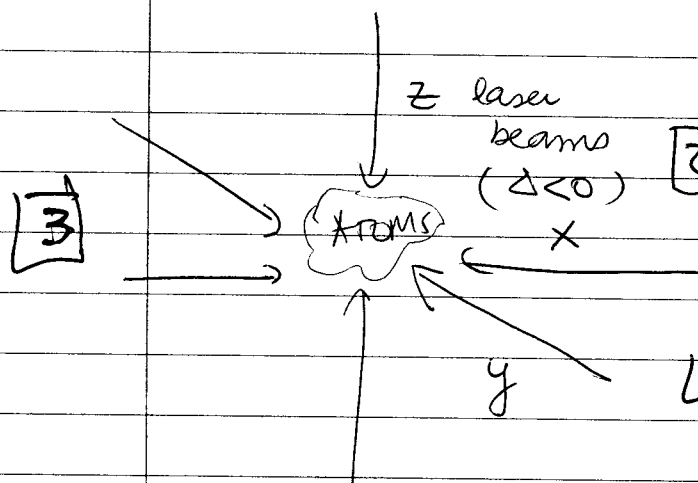
(10)

[3]

(c) The laser-beam configuration in order to obtain optical molasses consists of three pairs of ~~counter-propagating~~ red-detuned laser beams in the x, y and z direction. In each pair, there is one counter-propagating and one co-propagating beam with regard to the atoms.

[1]

ing and one co-propagating beam with regard to the atoms.



In each direction, because of the Red detuning, the

[2] atoms will experience a

viscous force, which will effectively cool them.

[1] Three pairs of beams guarantee this cooling is nearly isotropic.

[1]

The above set up cools, but not traps atoms.

[2]

In order for the atoms to be trapped, it would be necessary to confine them in a potential minimum by using, for instance, a restoring force.

[2]

This can be achieved by ~~adding~~ ^{adding} an inhomogeneous magnetic field and adequately ~~placed~~ ^{aligned} laser beams, ~~in a~~ ^{in a} ~~magneto-optical trap~~ ^{magneto-optical trap}. to the optical-molasses set up. This would give rise to a magneto-optical trap.

(15)

The course of the displaced atom

(a) Let us consider the matrix elements

$$\vec{d}_1 = \langle \vec{p} + \vec{A}(t) | \vec{r} | g \rangle \quad \text{and} \quad \vec{d}_2 = \langle \vec{p} + \vec{A}(t) | \vec{r} | g_{ro} \rangle$$

We will first write d_1, d_2 in the position space. For that purpose, we will need the closure relation

[1]

$$\int d^3r |\vec{r}\rangle \langle \vec{r}| = 1$$

Inserting this in d_1 yields

$$\vec{d}_1 = \int d^3r \langle \vec{p} + \vec{A}(t) | \vec{r} \rangle \vec{r} \langle \vec{r} | g \rangle =$$

[3]

$$= \frac{1}{(2\pi)^{3/2}} \int \frac{e^{-i[\vec{p} + \vec{A}(t)] \cdot \vec{r}}}{(2\pi)^{3/2}} \vec{r} \psi_g(\vec{r})$$

(1 mark for each correct step)

Similarly,

[3]

$$\vec{d}_2 = \int d^3r \langle \vec{p} + \vec{A}(t) | \vec{r} \rangle \vec{r} \langle \vec{r} | g_{ro} \rangle = \int d^3r \frac{e^{-i[\vec{p} + \vec{A}(t)] \cdot \vec{r}}}{(2\pi)^{3/2}} \vec{r} \psi_g(\vec{r} - \vec{r}_0)$$

[1]

By shifting $\vec{r} \rightarrow \vec{r} - \vec{r}_0$, d_2 becomes

$$\vec{d}_2 = \frac{1}{(2\pi)^{3/2}} \int d^3r e^{-i[\vec{p} + \vec{A}(t)] \cdot (\vec{r} + \vec{r}_0)} (\vec{r} + \vec{r}_0) \psi_0(\vec{r}) \quad (*)$$

[2]

$$= \frac{1}{(2\pi)^{3/2}} e^{-i[\vec{p} + \vec{A}(t)] \cdot \vec{r}_0} \left[\underbrace{\int d^3r e^{-i[\vec{p} + \vec{A}(t)] \cdot \vec{r}} \vec{r} \psi_0(\vec{r})}_{(**)} + \vec{r}_0 \int d^3r e^{i[\vec{p} + \vec{A}(t)] \cdot \vec{r}} \psi_0(\vec{r}) \right]$$

[2]

Note that $(**) = (2\pi)^{3/2} \langle \vec{p} + \vec{A}(t) | \vec{g} \rangle$, $(*) = (2\pi)^{3/2} \vec{d}_1$

This gives

$$\boxed{2} \quad \vec{d}_2 = \underbrace{e^{-i[\vec{p} + \vec{A}(t)] \cdot \vec{r}_0}}_{\text{overall phase}} \underbrace{[\vec{d}_1 + \vec{r}_0 \langle \vec{p} + \vec{A}(t) | g \rangle]}_{\text{term dependent on } r_0}$$

(b) Physically, both terms in $\vec{d}_2$ will lead to changes in the SFA transition probability. They are clearly artifacts, as it should not matter how the origin of a coordinate system is chosen.

One can readily see that both transition probabilities are different:

Transition probability obtained with $\vec{d}_1$:

$$\boxed{1} \quad |M^{(1)}_{\text{SFA}}|^2 = \left| \int_{t_0}^{\infty} dt \, \vec{d}_1 \cdot \vec{E}(t) e^{-i \int_{t_0}^t [\vec{p} + \vec{A}(z)] \cdot \vec{r}_0 dz - i E_g(t-t_0)} \right|^2$$

$i\phi(\vec{p}, t, t_0)$

Transition probability obtained with $\vec{d}_2$

$$\boxed{3} \quad |M^{(2)}_{\text{SFA}}|^2 = \left| \underbrace{e^{-i\vec{p} \cdot \vec{r}_0}}_{\substack{\text{just} \\ \text{a phase}}} \int_{t_0}^{\infty} dt \, e^{-i\vec{A}(t) \cdot \vec{r}_0} [\vec{d}_1 + \vec{r}_0 \langle \vec{p} + \vec{A}(t) | g \rangle] \cdot \vec{E}(t) e^{i\phi} \right|^2$$

$$= \left| \int_{t_0}^{\infty} dt \, e^{-i\vec{A}(t) \cdot \vec{r}_0} \vec{d}_1 \cdot \vec{E}(t) e^{i\phi(\vec{p}, t, t_0)} \right|^2 +$$

$$+ \left| \int_{t_0}^{\infty} \vec{r}_0 \cdot \vec{E}(t) \langle \vec{p} + \vec{A}(t) | g \rangle e^{-i\vec{A}(t) \cdot \vec{r}_0} e^{i\phi} \right|^2 +$$

Interference terms

$$\neq |M^{(1)}_{\text{SFA}}|^2$$

(9)

The time dependent phase $e^{-i\vec{A}(t) \cdot \vec{r}_0}$ will lead to spurious oscillations. It is directly related with the SFA's lack of gauge dependence.

The $\vec{r}_0$ dependent term is an artifact which appears because in the SFA the continuum and the bound states are not orthogonal.

In fact, for an exact continuum state $|\phi_c\rangle$, $\langle \phi_c | g \rangle = 0$. This would eliminate this term.

On the other hand,

$$\langle \vec{p} + \vec{A}(t) | g \rangle = \frac{1}{(2\pi)^{3/2}} \int e^{-i[\vec{p} + \vec{A}(t)] \cdot \vec{r}} \psi_g(\vec{r}) d\vec{r} \neq 0.$$

1

This causes the above-stated problems