

Using Quantile Regression to Set Thresholds for Extreme Value Analyses

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With thanks to Philip Jonathan (Shell Research) and Nicolas Attalides (UCL)

Outline



- 1. Wave height data → design of safe marine structures.
- 2. Threshold-based extreme value modelling.
- 3. Quantile regression \rightarrow thresholds for extreme value regression models.
- 4. Wave height data.

Wave heights (at an unnamed location)

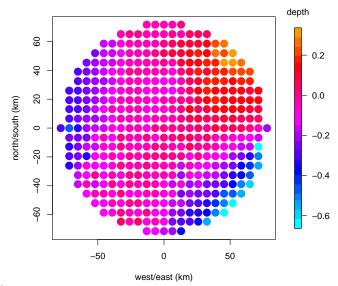


- Hindcasts of storm peak significant wave height (Y).
 - wave height: trough to the crest of the wave;
 - significant wave height: the average of the largest third of wave heights. A measure of sea surface roughness;
 - storm peak: largest value from each 'storm' identified;
 - assume storms are approximately independent.
- 427 sites : within \approx 80km of site of interest.
- 1970 2007 : 76 storms .
- Storms occur between November and May.
- $\bullet \approx$ 2 storms per year, at each site, on average.
- Potential covariates: water depth, longitude, latitude.

For confidentiality Y has been scaled to [0, 100].

(Scaled) water depth and location





Wave heights

Storm damage





Wave heights 5/35

Storm damage



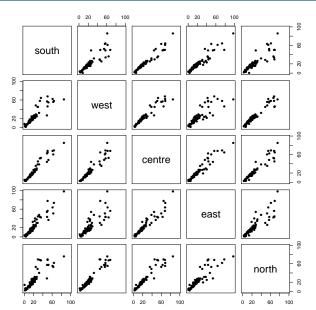


At the centre of the grid of data (where scaled water depth = 0)

- How large will significant wave heights be in the next 100 years? ... or the next 1000 years?
- Estimate extreme quantiles (upper tail).
- Issues: pooling of spatially-dependent data over space; effect of water depth; extrapolation.

Spatial dependence in sig. wave height

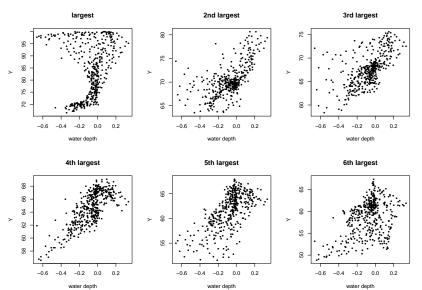




Wave heights

Effect of water depth

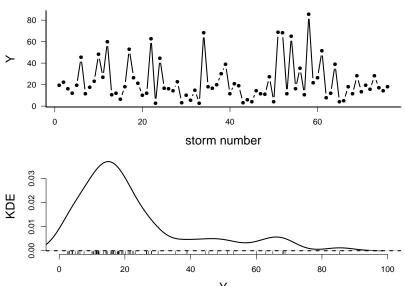




Wave heights 7/35

Storm peaks at centre of grid

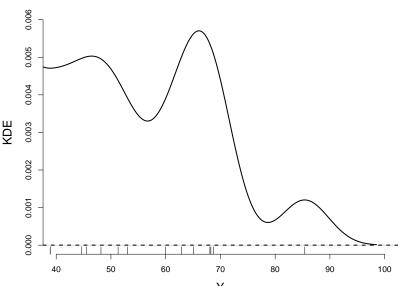




Wave heights

Zoom in on upper tail





Wave heights

Extreme Value Modelling



Possibilities:

• Fit a model to all the data. Extrapolate from this model.

...but (unless the link between typical and atypical behaviour is well-understood) inferences about extremes could be influenced adversely by the modelling of non-extreme data.

EV modelling 10/3

Extreme Value Modelling



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- Fit a model to all the data. Extrapolate from this model.
 - ...but (unless the link between typical and atypical behaviour is well-understood) inferences about extremes could be influenced adversely by the modelling of non-extreme data.
- Base inferences about future extreme behaviour on extreme data:
 - block maxima;
 - r-largest order statistics in a block;
 - exceedances of a high threshold, u.

EV modelling 10/3

Block maxima



Assume that Y_1, Y_2, \dots are i.i.d..

Let $M_N = \max(Y_1, \dots, Y_N)$.

• Any possible (non-degenerate) distribution of $Z_N = (M_N - b_N)/a_N$ as $N \to \infty$ is in the GEV (Generalised Extreme Value) family, with c.d.f.

$$P(Z_N \leqslant z) = \exp\left\{-\left[1 + \xi\left(\frac{z - \mu_N}{\sigma_N}\right)\right]_+^{-1/\xi}\right\},$$

where $x_+ = \max(x, 0)$ and $\sigma > 0$.

Block maxima



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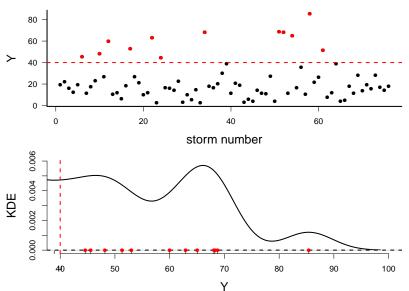
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- Suggests GEV(μ_N , σ_N , ξ) as a model for M_N for large N.
- Upper end point is finite for $\xi < 0$ and infinite for $\xi \geqslant 0$.
- Related asymptotic model for *r*-largest order statistics.

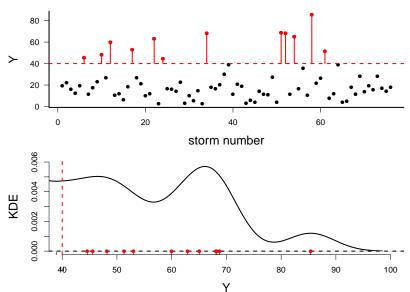
Threshold exceedances, u=40





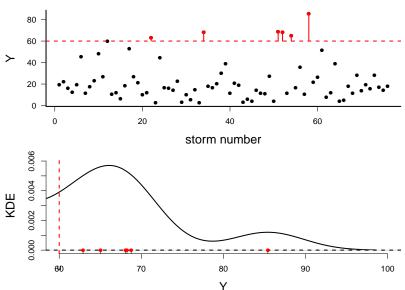
Threshold excesses, u=40





Threshold excesses, u=60





Threshold exceedances I: binomial-GP

UCL

• How often is a (high) threshold *u* exceeded?

Let $p_u = P(Y > u)$.

Threshold exceedances I: binomial-GP



- How often is a (high) threshold u exceeded?
 Let p_u = P(Y > u).
- Given that *u* is exceeded, by how much is it exceeded?

Any possible distribution of $(Y - u) \mid Y > u$ as $u \to \infty$ is in the Generalised Pareto (GP) family, with conditional c.d.f.

$$P(Y \leqslant u \mid Y > u) = 1 - \left(1 + \frac{\xi y}{\sigma_u}\right)_+^{-1/\xi},$$

where $\sigma_u > 0$.

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If $Y_1, Y_2, ..., Y_n$ are independent then this suggests a binomial-GP model, for sufficiently high u.

Threshold exceedances II: NHPP



- We rescale time (storm number) to (0,1) and let $M(t_1, t_2, u)$ be the number of observations in $[t_1, t_2] \times (u, \infty)$.
- Asymptotic arguments lead to a 2D non-homogeneous Poisson process NHPP(μ_N, σ_N, ξ) model, s.t.

$$M(t_1, t_2, u) \sim \text{Poisson}\left(\frac{n}{N}(t_2 - t_1)\left[1 + \xi\left(\frac{u - \mu_N}{\sigma_N}\right)\right]_+^{-1/\xi}\right).$$

• Here, we choose N = n = 76 so that (μ_N, σ_N, ξ) relate to maximum on dataset.

Informally ...

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1. Reparameterise: $(p_u, \sigma_u, \xi) \rightarrow (\mu_N, \sigma_N, \xi)$, using

$$\sigma_{u} = \sigma_{N} + \xi(u - \mu_{N});$$
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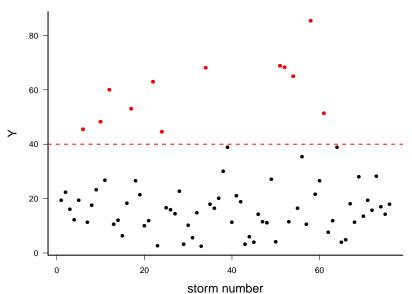
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2. Poisson \approx binomial, for large n, small p_{ii} .

NHPP on $(60, \infty)$





EV modelling

Extreme value regression modelling



What if we have covariate effects?

- Appeal to standard theory conditional on the covariates.
- Specify that extreme value parameters, e.g. μ_N , σ_N , ξ are functions of the value of a covariate x, e.g.

NHPP($\mu_N(x), \sigma_N(x), \xi(x)$).

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NHPP(
$$\mu_N(x), \sigma_N(x), \xi(x)$$
).

• The PP model has the advantage (over the bin-GP model) that its parameters are invariant to *u*.

... but does a constant threshold still make sense?



Arguments for:

• Asymptotic justification : the threshold u(x) needs to be high for each x.



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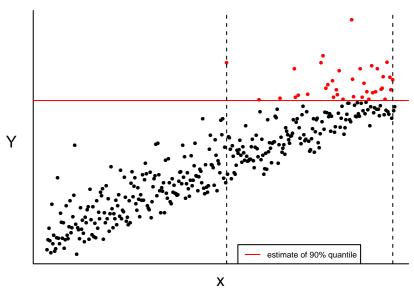
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Set u(x) so that $p_u(x) = P(Y > u(x))$, is approx. constant for all x.

- Set u(x) by trial-and-error or by discretising x, e.g. different threshold for different locations, months etc.
- Quantile regression (QR): model quantiles of Y as a function of covariates.

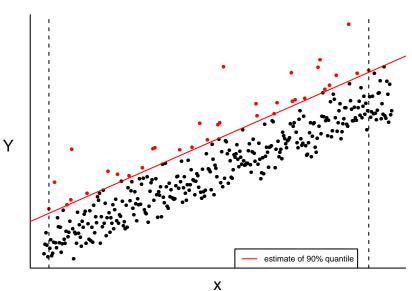
Constant threshold





Quantile regression





QR and NHPP model parameterisation



Let $p_u(x) = P(Y > u(x))$. Then, if $\xi(x) = \xi$ is constant,

$$p_u(x) \approx \frac{1}{N} \left[1 + \xi \left(\frac{u(x) - \mu(x)}{\sigma(x)} \right) \right]^{-1/\xi}.$$

If $p_u(x) = p_u$ is constant then

$$u(x) = \mu(x) + c \, \sigma(x).$$

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The form of u(x) is determined by the extreme value model:

- if $\mu(x)$ and/or $\sigma(x)$ are linear in x: linear QR;
- if $\log \mu(x)$ and/or $\log \sigma(x)$ is linear in x: non-linear QR.

Return to significant wave height data



 Fit NHPP regression model using maximum likelihood: model effects on EV parameters as simple functions of (scaled) water depth x, e.g.

$$\mu(\mathbf{x}) = \mu_0 + \mu_1 \mathbf{x}.$$

- Assume $\xi > -1/2$ for regularity.
- Threshold: use quantile regression to achieve approx. constant probability p_u of threshold exceedance over space:

Model $100(1 - p_{tt})\%$ quantile as a function of covariates.

- Spatial dependence
 - Not modelled explicitly: interest in one location only.
 - Initially, assume conditional independence of responses given covariate values.
 - Adjust standard errors etc. for spatial dependence.
 - ... Chandler and Bate (2007): scale log-likelihood so that Hessian at MLE matches "sandwich" estimator of var(MLE).

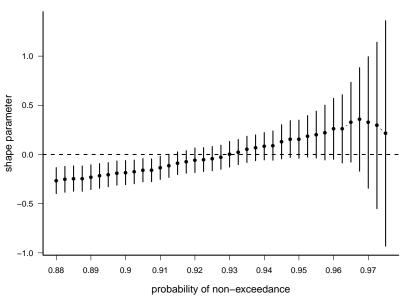
Threshold selection



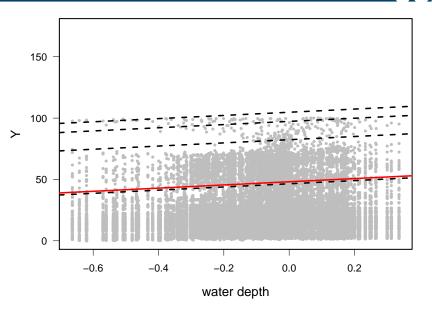
- Threshold level (determined by p_{ij}): bias-variance trade-off.
- Iterative: form of threshold depends on NHPP covariate model.
- For given EV model set threshold using appropriate QR model.
- Treat QR threshold as fixed: simulation study (Northrop and Jonathan, 2011) suggests effect of ignoring uncertainty is minimal.
- Choice of exceedance probability p_u : look for stability in parameter estimates.
- Final model: μ linear in water depth, σ and ξ constant.

MLEs of shape parameter ξ vs. 1 - p.

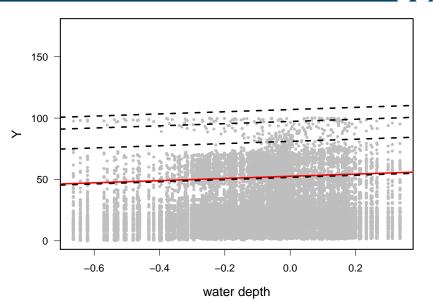




87% *u(x)* and NHPP: 99%, 99.9%, 99.99% **LICL**

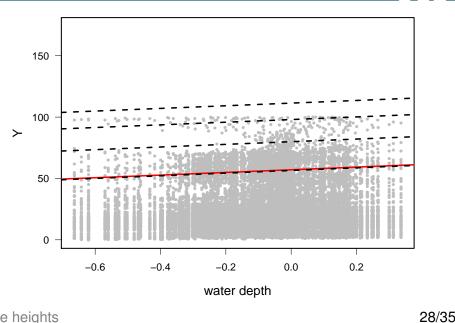


89% *u(x)* and NHPP: 99%, 99.9%, 99.99% **LICL**

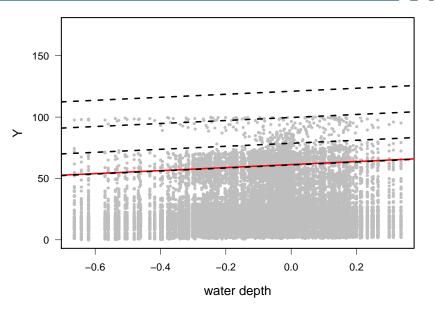


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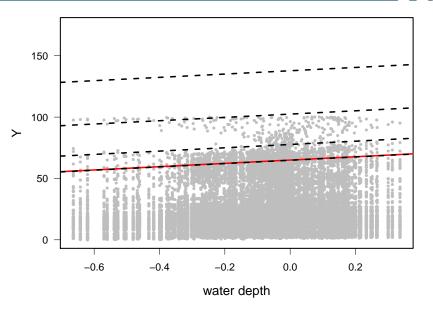
91% *u(x)* and NHPP: 99%, 99.9%, 99.99%



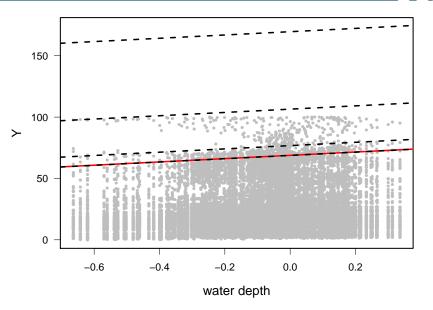
93% *u(x)* and NHPP: 99%, 99.9%, 99.99% **UCL**



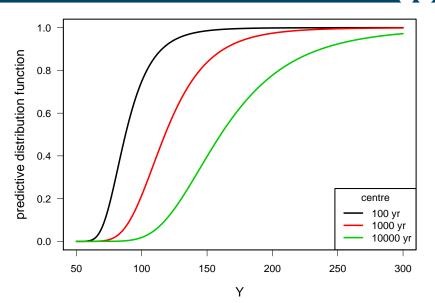
95% u(x) and NHPP: 99%, 99.9%, 99.99%



97% *u(x)* and NHPP: 99%, 99.9%, 99.99% **≜UCL**

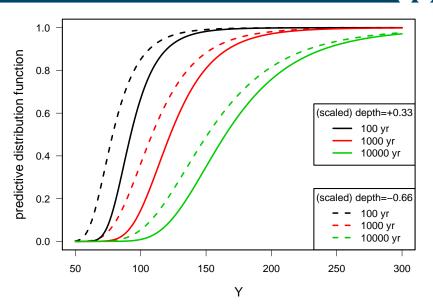


Approx. predictive DF of *m*-year maximum



Wave heights 32/35

Approx. predictive DF of *m*-year maximum



Wave heights 33/35

Concluding remarks



Quantile regression

- A simple and effective strategy to set thresholds for non-stationary EV models.
- Theoretical work (Nicolas Attalides):
 - Suppose that $\mu(x_1, ..., x_q) = \mu_0 + \sum_{i=1}^q \mu_i x_i$.
 - If each of the q covariates are distributed symmetrically then a QR-threshold minimizes the generalised asymptotic variance of $(\widehat{\mu}_1,\ldots,\widehat{\mu}_q)$.
 - (...but this doesn't address bias).

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Ongoing work

- Address bias-variance tradeoff.
- Threshold sensitivity/uncertainty. Extend Wadsworth and Tawn (2012) to regression siutation.

References



Chandler, R. E. and Bate, S. B. (2007) Inference for clustered data using the independence loglikelihood. *Biometrika* **94** (1), 167–183.

Eastoe, E. F. and Tawn J. A. 2009. Modelling non-stationary extremes with application to surface level ozone. *Applied Statistics* **58 (1)**, 2545.

Koenker R. 2009. *Quantreg: Quantile Regression. R Package Version 4.44.* http://CRAN.R-project.org/package=quantreg

Northrop, P. J. and Jonathan, P. Threshold modelling of spatially-dependent non-stationary extremes with application to hurricane-induced wave heights. Published online in *Environmetrics*. **22 (7)**, 799–809 (with discussion.)

Wadsworth, J. and J. Tawn (2012). Likelihood-based procedures for threshold diagnostics and uncertainty in extreme value modelling. *Journal of the Royal Statistical Society - Series B: Statistical Methodology* **74 (3)**, 543–567.

Thank you for your attention.