

# Sheet 1: Examples and exponentials

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## Question 1.

Prove that the following are equivalent:

- (a)  $A \in O(n)$  (recall that  $A \in O(n)$  if and only if  $A^T A = 1$ ),
- (b)  $(Av) \cdot (Aw) = v \cdot w$  for all  $v, w \in \mathbf{R}^n$ ,
- (c)  $|Av|^2 = |v|^2$  for all  $v \in \mathbf{R}^n$ .

**Question 2.** (a) Find the exponential of the matrix  $H = \begin{pmatrix} 0 & x & z \\ 0 & 0 & y \\ 0 & 0 & 0 \end{pmatrix}$ .

(b) Given a matrix  $K = \begin{pmatrix} 1 & a & c \\ 0 & 1 & b \\ 0 & 0 & 1 \end{pmatrix}$ , find a matrix  $H$  such that  $\exp(H) = K$ .

(c) Compute  $\exp \begin{pmatrix} x & y \\ 0 & 0 \end{pmatrix}$ .

**Question 3.** Given  $v = (x, y, z)$ , consider the matrix

$$K_v := \begin{pmatrix} 0 & -z & y \\ z & 0 & -x \\ -y & x & 0 \end{pmatrix}.$$

- (a) Show that if  $u \in \mathbf{R}^3$  then for any  $v \in \mathbf{R}^3$ ,  $K_u v = u \times v$ .
- (b) Hence or otherwise, show that if  $|u|^2 = 1$  then  $K_u^3 = -K_u$  (Hint: Recall that  $a \times (b \times c) = b(a \cdot c) - c(a \cdot b)$ .)
- (c) Show that if  $|u|^2 = 1$  then  $\exp(\theta K_u) = 1 + K_u \sin \theta + (1 - \cos \theta) K_u^2$  and check that

$$(\star) \quad \exp(\theta K_u) v = v \cos \theta + (u \times v) \sin \theta + (1 - \cos \theta)(u \cdot v)u.$$

( $\star$ ) is Rodrigues's formula for the rotation of  $v$  by an angle  $\theta$  around  $u$ .

(d) Show by direct computation that  $[K_u, K_v] := K_u K_v - K_v K_u = K_{u \times v}$  for any  $u, v \in \mathbf{R}^3$ .

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The last two questions concern the group  $SU(2)$  of unitary 2-by-2 matrices with determinant 1 and its Lie algebra  $\mathfrak{su}(2)$  of 2-by-2 skew-Hermitian matrices with trace zero.

For  $v = (x, y, z) \in \mathbf{R}^3$  we define

$$M_v := \begin{pmatrix} ix & y + iz \\ -y + iz & -ix \end{pmatrix} \in \mathfrak{su}(2).$$


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**Question 4.** Show that  $M_u M_v = -(u \cdot v)1 + M_{u \times v}$ . Deduce that if  $|u|^2 = 1$  then  $M_u^2 = -1$  and hence that

$$\exp(\theta M_u) = (\cos \theta)1 + \sin \theta M_u = \begin{pmatrix} \cos \theta + ix \sin \theta & y \sin \theta + iz \sin \theta \\ -y \sin \theta + iz \sin \theta & \cos \theta - ix \sin \theta \end{pmatrix} \in SU(2).$$

**Question 5.** Consider the action of  $SU(2)$  on  $\mathfrak{su}(2)$  given by

$$\tilde{\rho}: SU(2) \times \mathfrak{su}(2) \rightarrow \mathfrak{su}(2), \quad \tilde{\rho}(g, m) = gm g^{-1}.$$

- (a) Show that this defines a 3-dimensional real representation  $\rho: SU(2) \rightarrow GL(\mathfrak{su}(2))$  of  $SU(2)$ .
- (b) Show that if  $\tilde{\rho}(g, M_v) = M_{v'}$  then  $|v'|^2 = |v|^2$ . (Hint: Compute determinants.)
- (c) Recall from Question 4 that if  $|u|^2 = 1$  then  $\exp(\theta M_u) = (\cos \theta)1 + \sin \theta M_u$ . Show that if  $u$  and  $v$  are vectors and  $|u|^2 = 1$  then

$$\tilde{\rho}(\exp(\theta M_u), M_v) = M_{v'}$$

where

$$v' = v \cos 2\theta + (u \times v) \sin 2\theta + (1 - \cos 2\theta)(u \cdot v)u.$$

In other words (Rodrigues's formula), the matrix  $\exp(\theta M_u)$  acts as a rotation around  $u$  by  $2\theta$ .

- (d) Let  $SO(3)$  denote the group of rotations of 3-dimensional space. Prove that the map  $\rho: SU(2) \rightarrow SO(3)$  is 2-to-1.

The representation  $\rho: SU(2) \rightarrow SO(3)$  is called the spin representation.